

# Networking

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Dependable Systems & Software  
Saarland University

Summer 04

Session B: Reliable Data Transfer

# Reliable Data Transfer

Read chapter 4 of [Holzmann 91] & chapter 3.3 of [Tanenbaum]

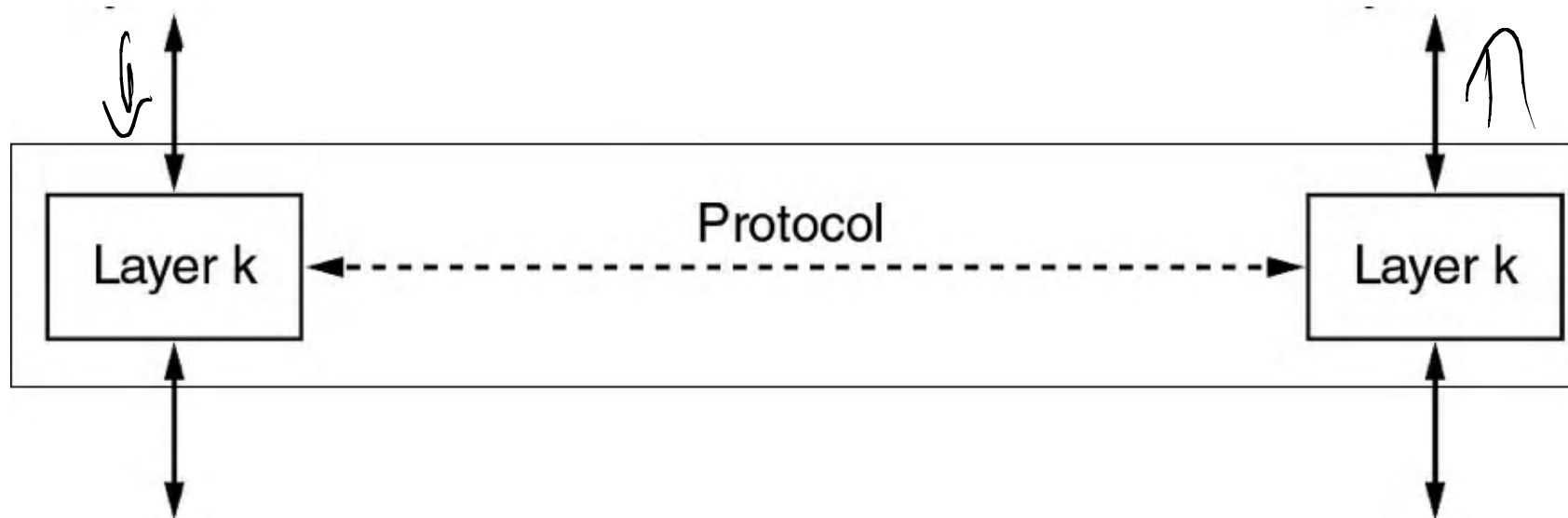
## Our goal today:

- ❑ develop a full reliable data transfer protocol
- ❑ approach:
  - add complexity step-by-step
  - introduce the ingredients

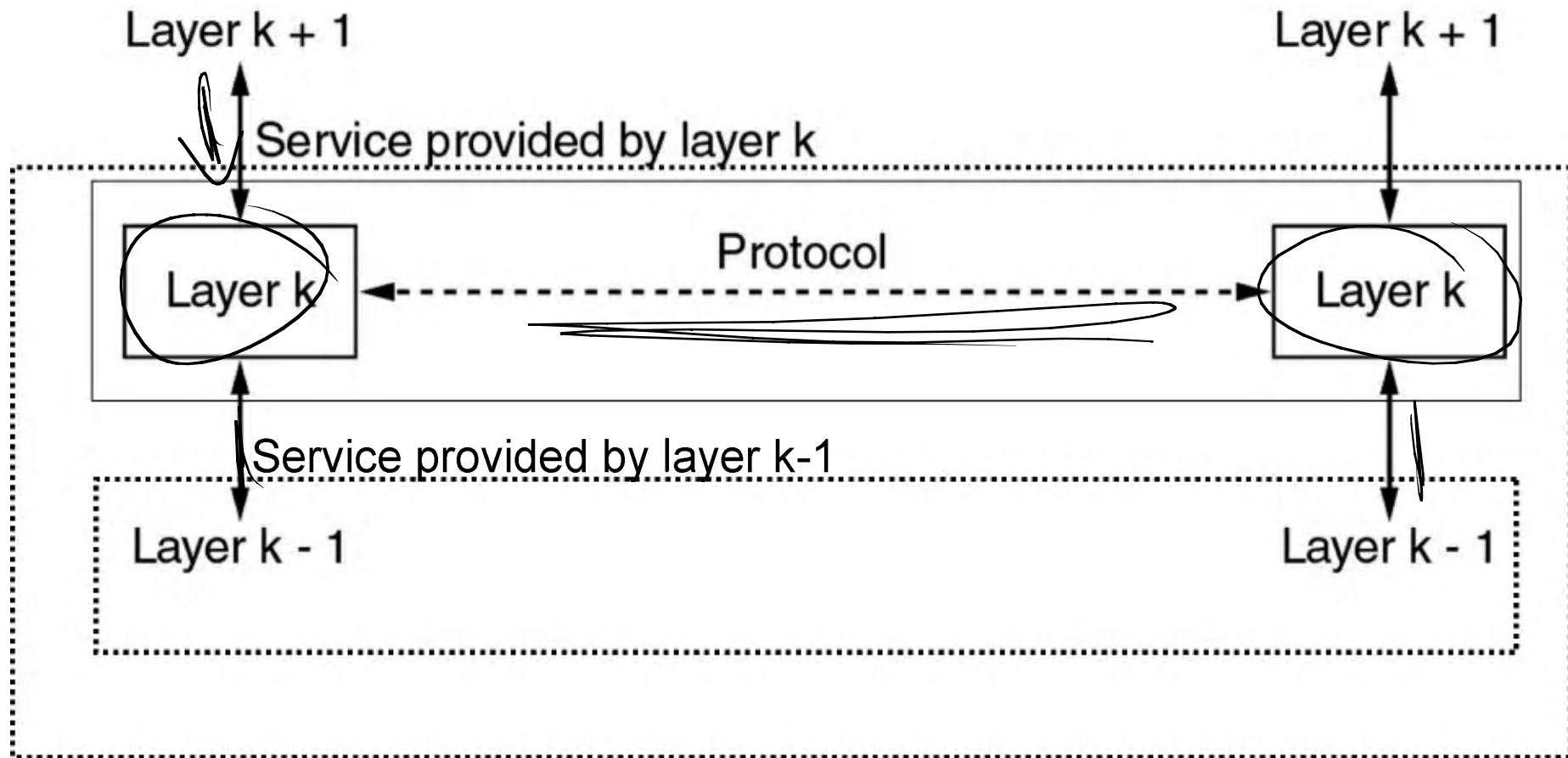
## Overview:

- ❑ Unrestricted simplex protocol
- ❑ simplex stop-and-wait
- ❑ windows, sequence numbers
- ❑ unreliable channels
- ❑ timers
- ❑ alternating-bit

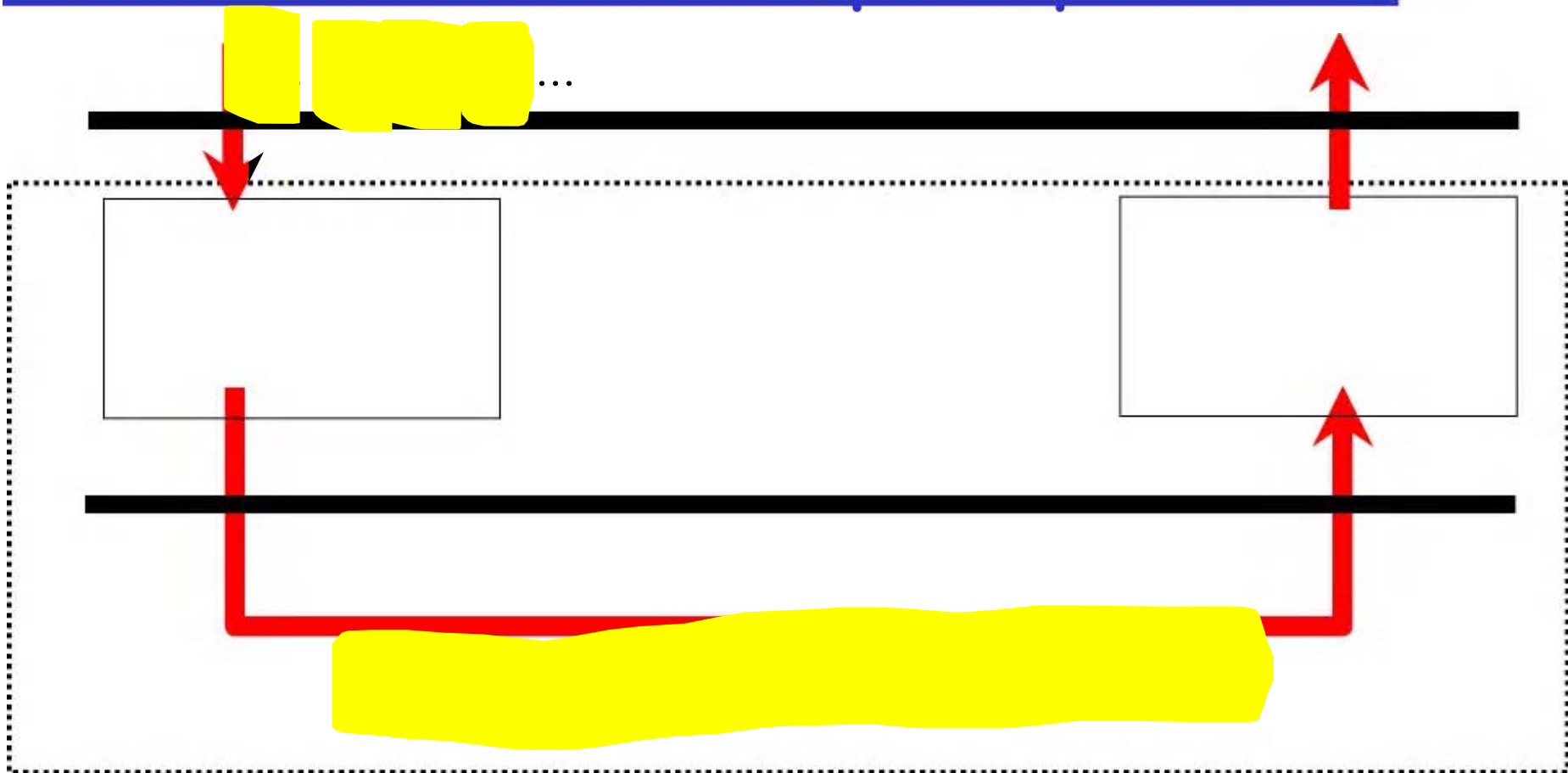
# Recall: Protocol, Environment and Services



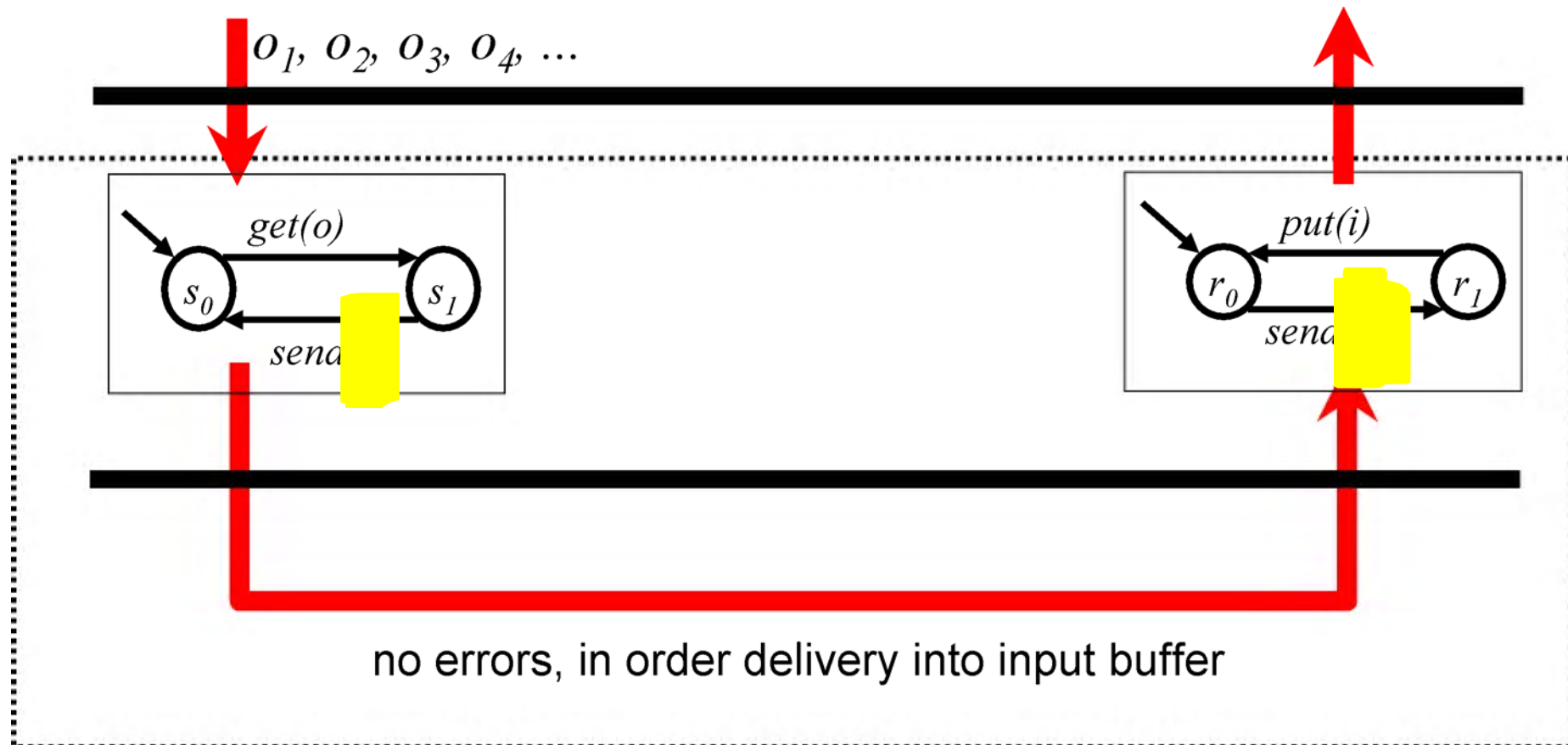
# Recall: Protocol, Environment and Services



# Getting started: An unrestricted simplex protocol



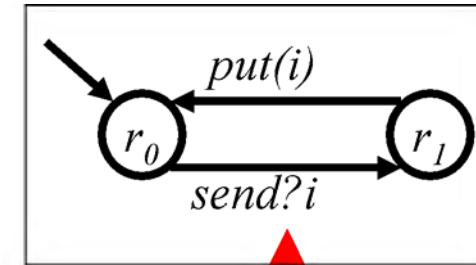
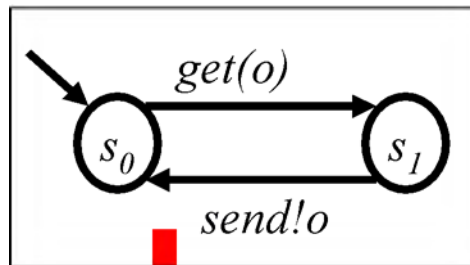
# Getting started: An unrestricted simplex protocol



# The same in C:

```
/* Protocol 1 (utopia) provides for data transmission in one direction only, from
sender to receiver. The communication channel is assumed to be error free
and the receiver is assumed to be able to process all the input infinitely quickly.
Consequently, the sender just sits in a loop pumping data out onto the line as
fast as it can. */
```

```
typedef enum {frame_arrival} event_type;
#include "protocol.h"
```



```
void sender1(void)
{
    frame s;          /* buffer for an outbound frame */
    packet buffer;   /* buffer for an outbound packet */

    while (true) {
        from_network_layer(&buffer); /* go get something to send */
        s.info = buffer;             /* copy it into s for transmission */
        to_physical_layer(&s);       /* send it on its way */
    }
    /* Tomorrow, and tomorrow
    Creeps in this petty pace
    To the last syllable of recorded time
    - Macbeth, V, v */
}

void receiver1(void)
{
    frame r;
    event_type event; /* filled in by wait, but not used here */

    while (true) {
        wait_for_event(&event); /* only possibility is frame_arrival */
        from_physical_layer(&r); /* go get the inbound frame */
        to_network_layer(&r.info); /* pass the data to the network layer */
    }
}
```

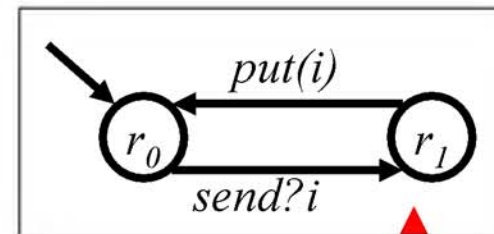
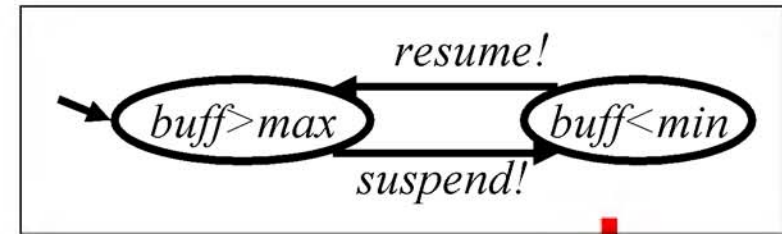
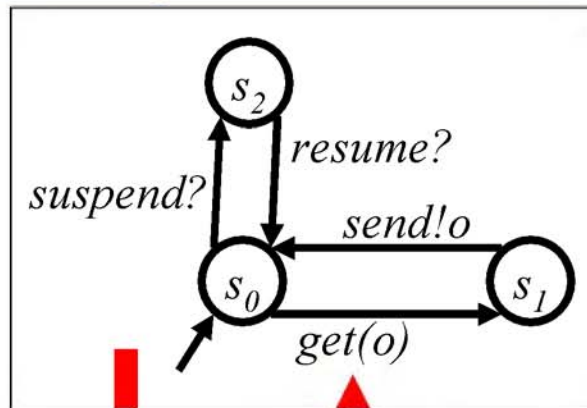
# Assessment:



- ❑ Works.
- ❑ Sender may pump out data as fast as possible.
- ❑ Receiver must be assumed to work infinitely fast, to prevent buffer overflow.
- ❑ Unrealistic!

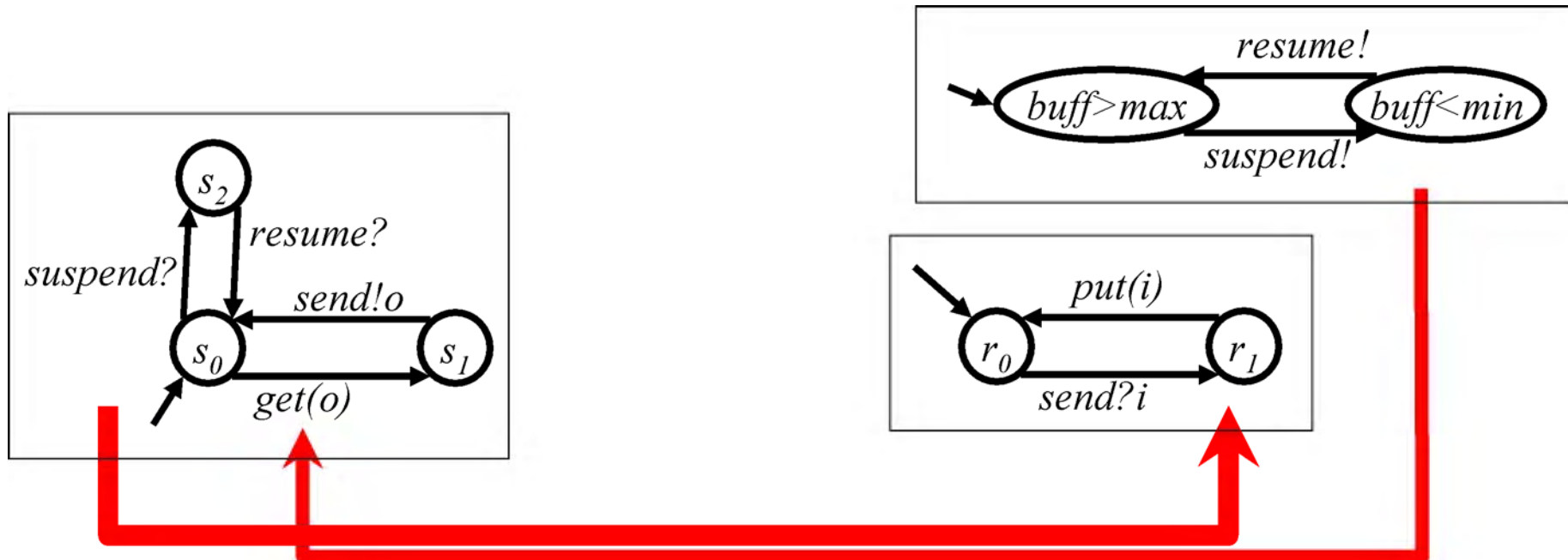


# 1st Revision: Simplex Suspend/Resume



- ❑ Unidirectional data-flow, but counterdirectional control-flow.
- ❑ Receiver now has finite buffer and processing speed, gives feedback - if buffer space runs out.
- ❑ Channel is still assumed error-free.

# Assessment:



- ❑ Delay of 'suspend' messages needs to be predictable, to prevent buffer overflow.
- ❑ Unrealistic!

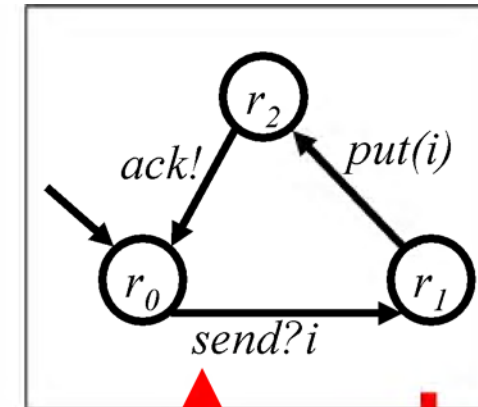
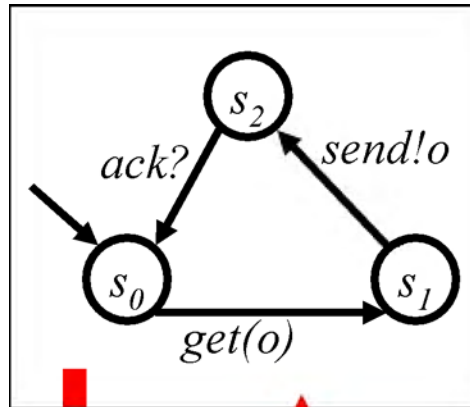
(Loss of resume message would make the system deadlock.)

## 2nd Revision: Simplex stop-and-wait



- ❑ Again, unidirectional data-flow, but counterdirectional control-flow.
- ❑ Receiver has finite buffer and processing speed, gives feedback - once data is processed,
- ❑ Sender awaits ACKs before sending next data item.
- ❑ Channel is still assumed error-free.

# The same in C:



```

void sender2(void)
{
    frame s;           /* buffer for an outbound frame */
    packet buffer;    /* buffer for an outbound packet */
    event_type event; /* frame_arrival is the only possibility */

    while (true) {
        from_network_layer(&buffer); /* go get something to send */
        s.info = buffer;             /* copy it into s for transmission */
        to_physical_layer(&s);      /* bye-bye little frame */
        wait_for_event(&event);     /* do not proceed until given the go ahead */
    }
}
  
```

```

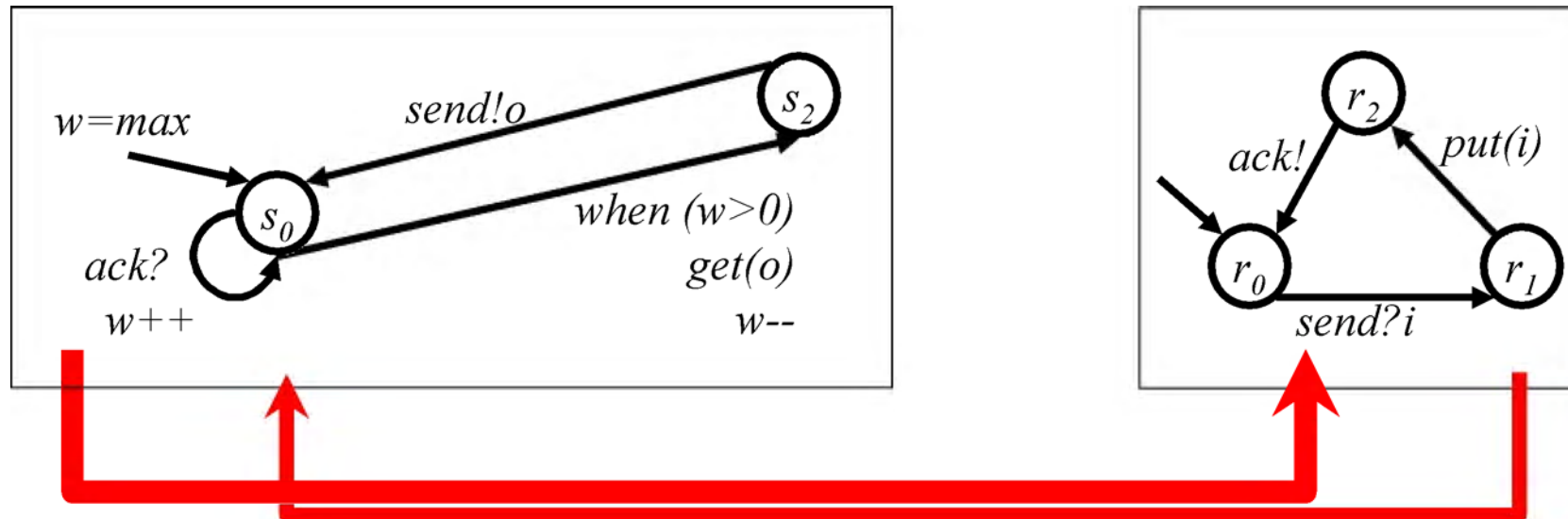
void receiver2(void)
{
    frame r, s;
    event_type event;
    while (true) {
        wait_for_event(&event); /* only possibility is frame_arrival */
        from_physical_layer(&r); /* go get the inbound frame */
        to_network_layer(&r.info); /* pass the data to the network layer */
        to_physical_layer(&s);    /* send a dummy frame to awaken sender */
    }
}
  
```

# Assessment:



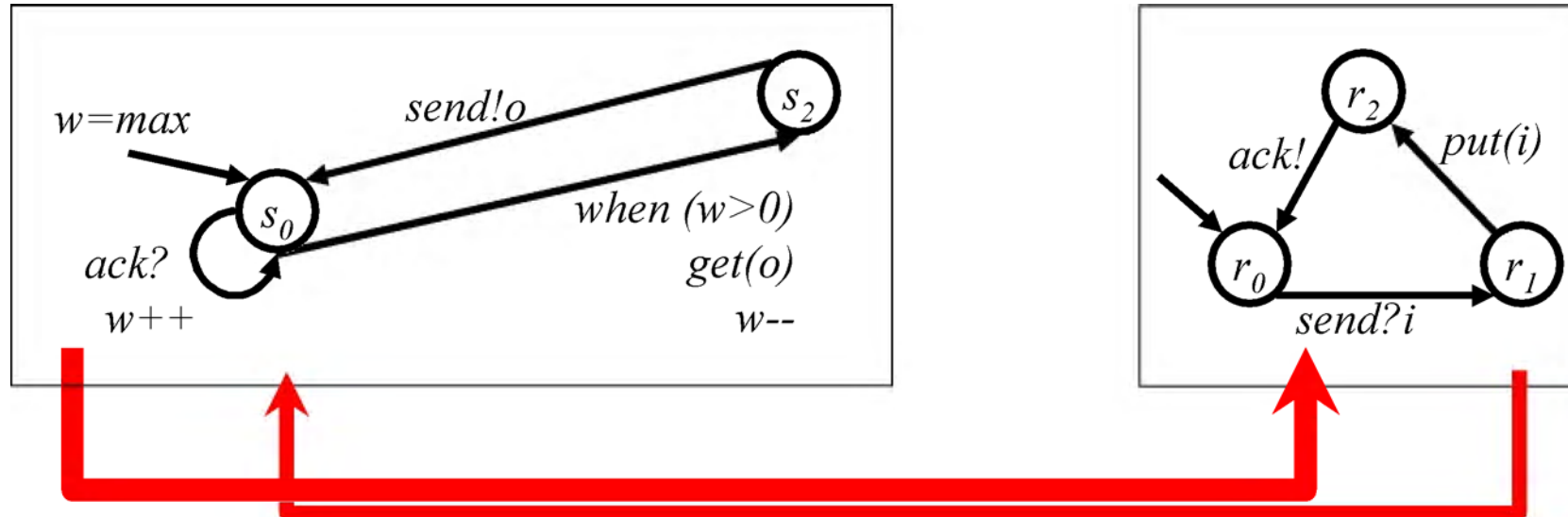
- Works fine, though not very efficient, under our assumption of a perfect channel.

## 3rd revision: adding a window



- Now the ACKs are decoupled from the sends. Sender maintains a worst-case estimate of the buffer space available at receiver.
- 'max' must be communicated from receiver to sender in initialisation phase.

# Assessment:



- ❑ Works fine, under our assumption of a perfect channel.
- ❑ This is a basic flow-control mechanism.

(Unfortunately the perfect channel assumption is unrealistic.)

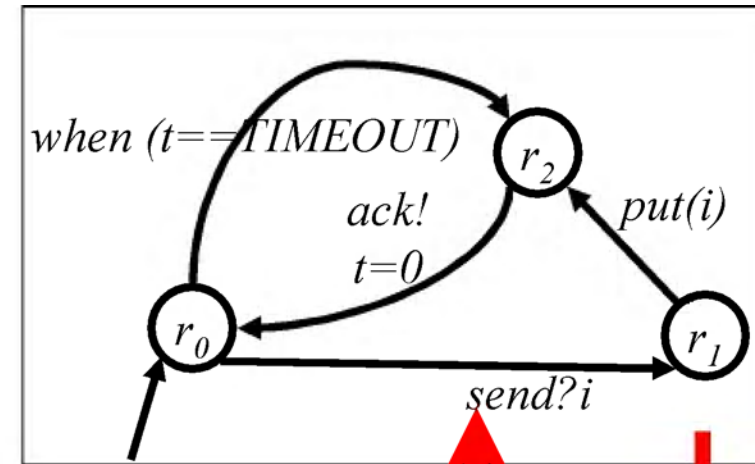
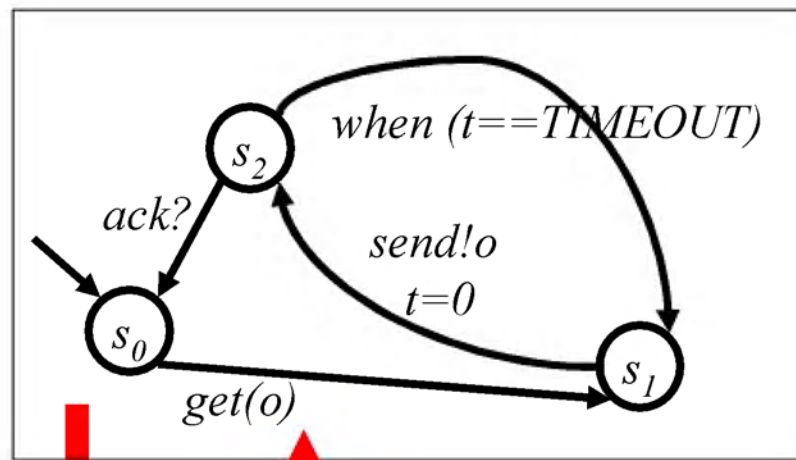
# Noisy channels

## Getting started:

- A noisy channel may corrupt messages, or *lose messages without any notification*  
(different from Session A, where silent losses were not considered)
  
- In the presence of potential losses, what to do?
  - Wait, wait, wait?
  - Send packets multiple times? When?
  
- The principal way out: **Timers and timeouts.**



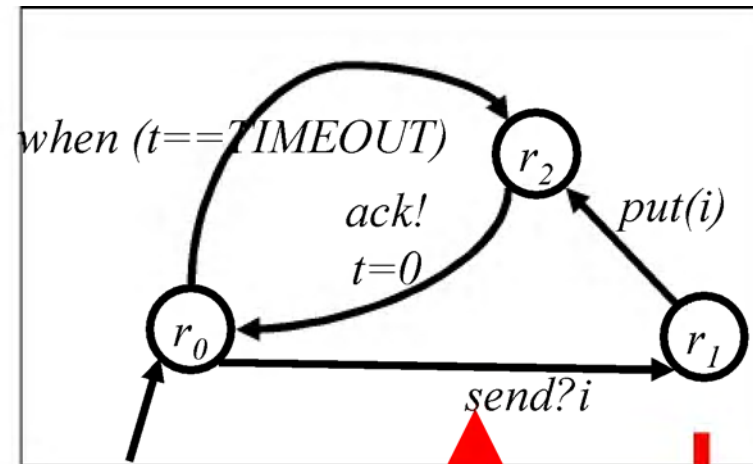
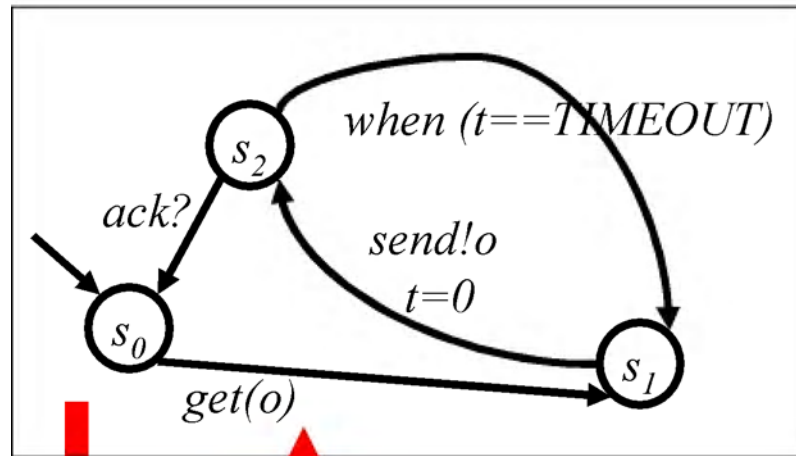
# 4th Revision: Simplex stop-and-wait over noisy channel



Assumption: Channel may corrupt messages, or lose messages without any notification.

Corrupted message  
are simply discarded  
as if they were lost.

# Assessment:



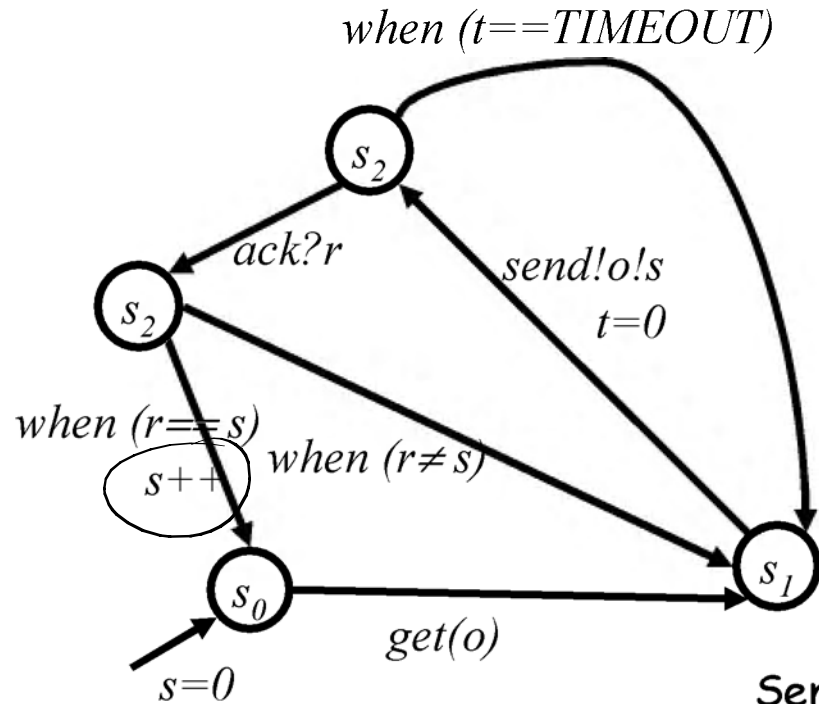
- ❑ It is still too simplistic and does not work. Think about it.
- ❑ The problem is that data may be duplicated because of lost ACKs.
- ❑ Hmhh. What is needed is a way to tell whether some data has been seen before.

👉 'sequence numbers'

# Sequence numbers

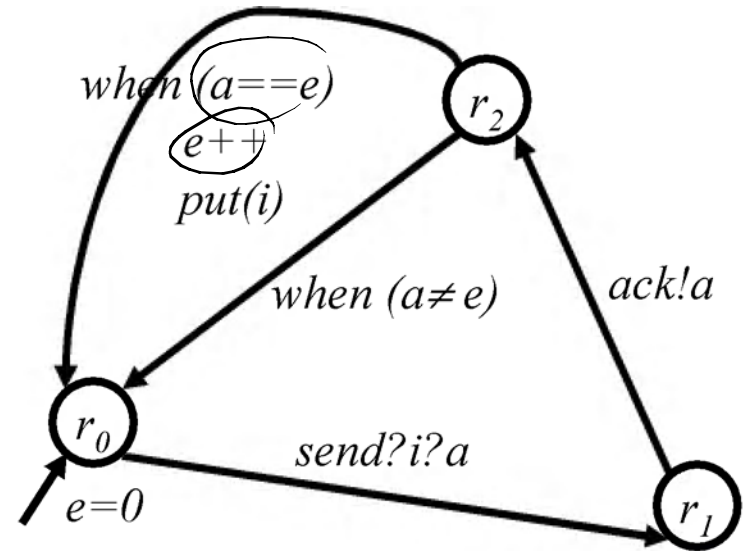
- ❑ The sender maintains a counter for the last message it has been sending, and waits for an acknowledgment for this message.
- ❑ Similar for receiver.
- ❑ The sender increments the counter with the message.
- ❑ The receiver echoes the counter back to the sender.
- ❑ Both check whether the counter was expected.

# 5th Revision: Simplex stop-and-wait with sequence numbers



Sender  
 s: last # sent  
 r: last # received

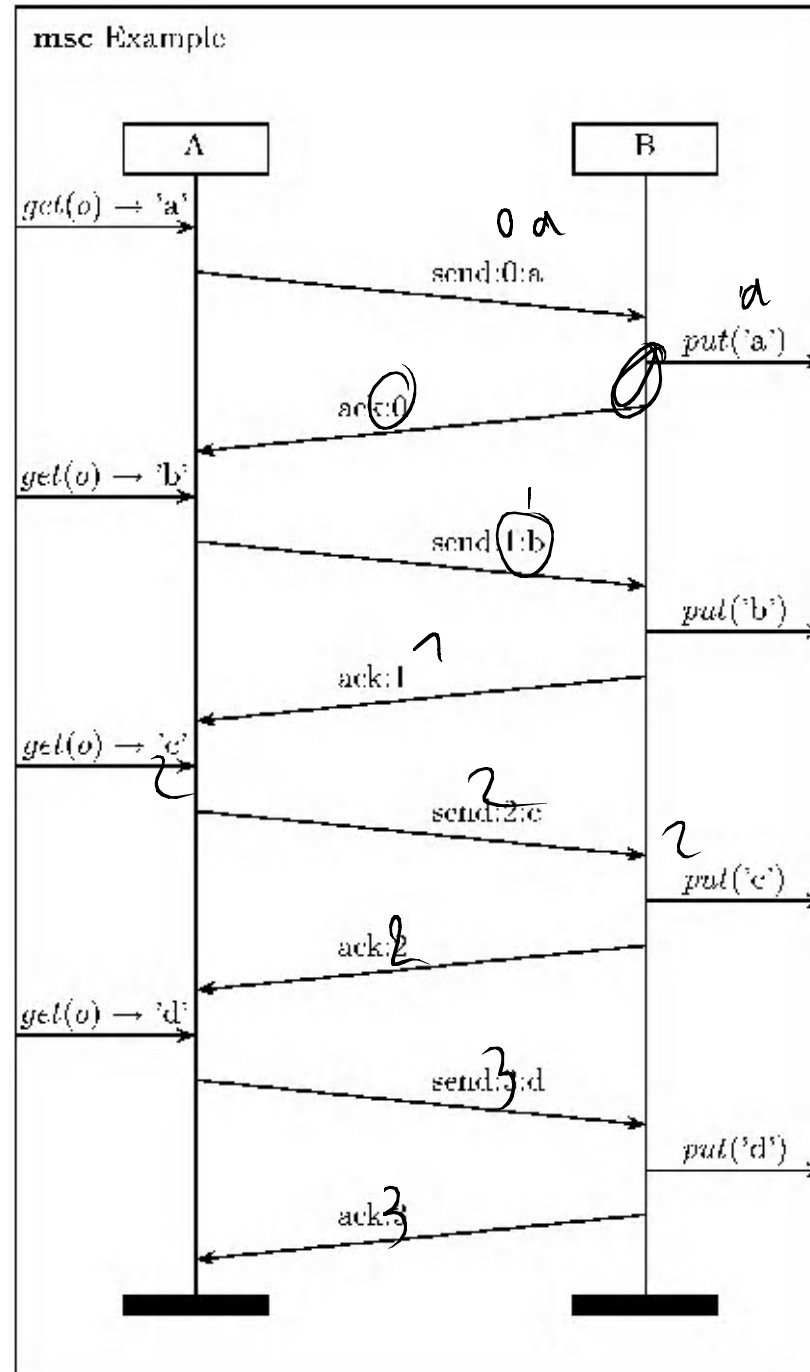
Receiver  
 e: next # expected  
 a: last # received

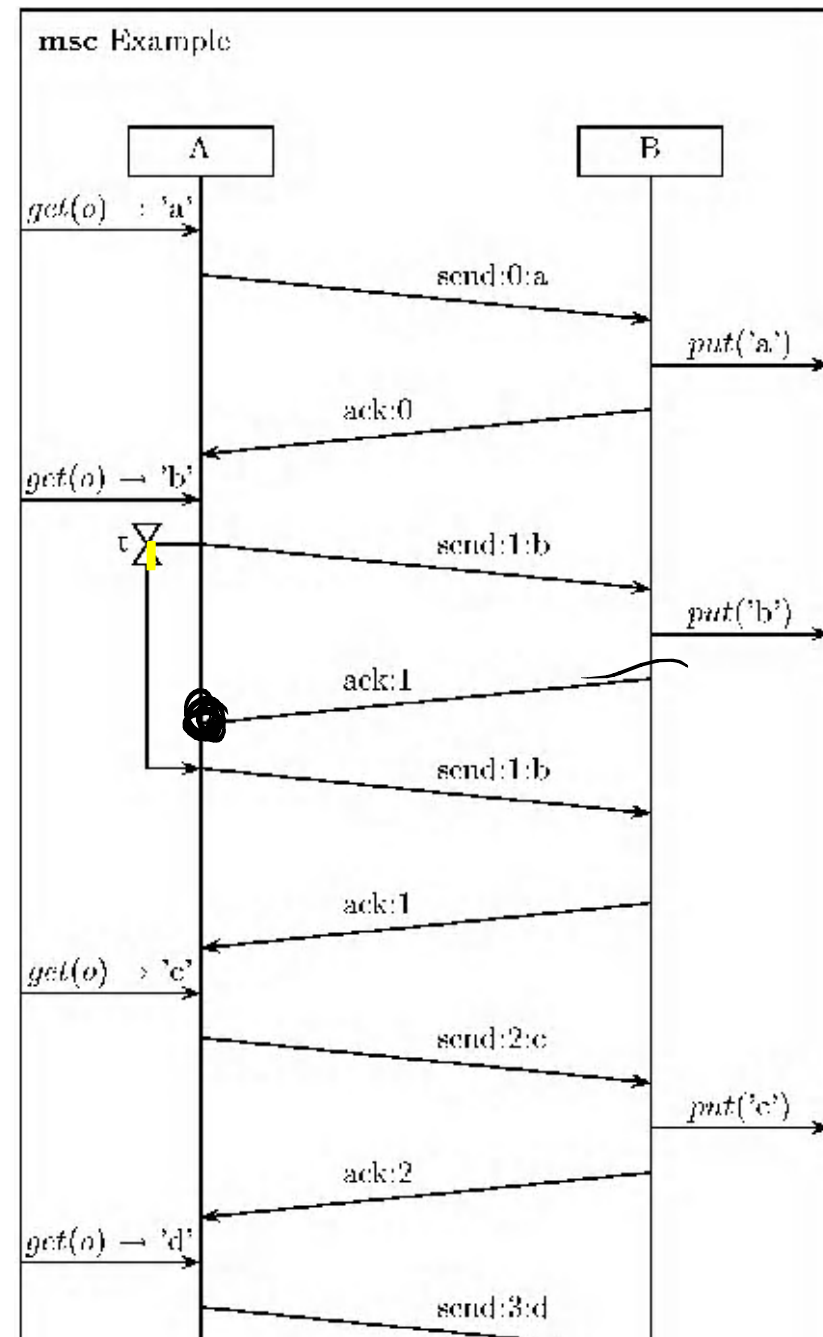
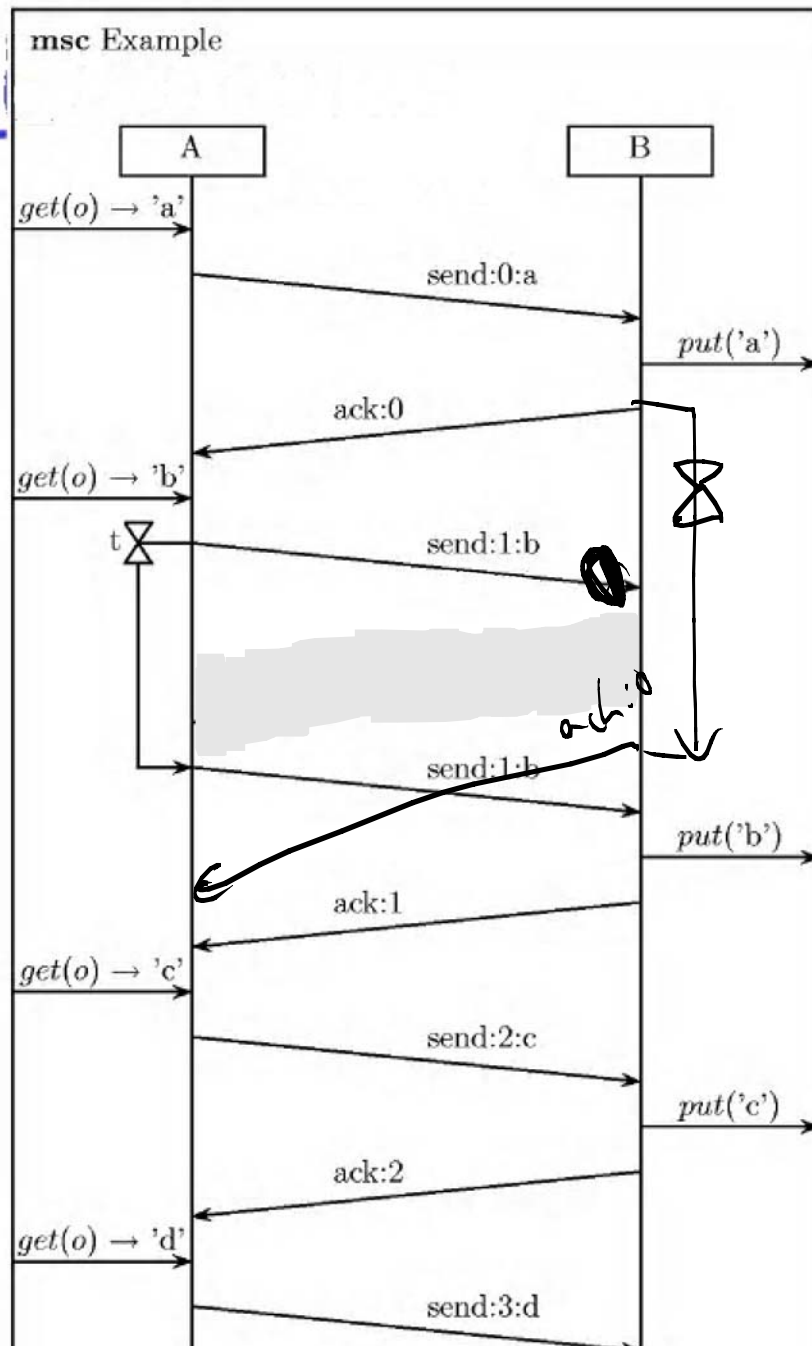


Corrupted message  
 are simply discarded  
 as if they were lost.

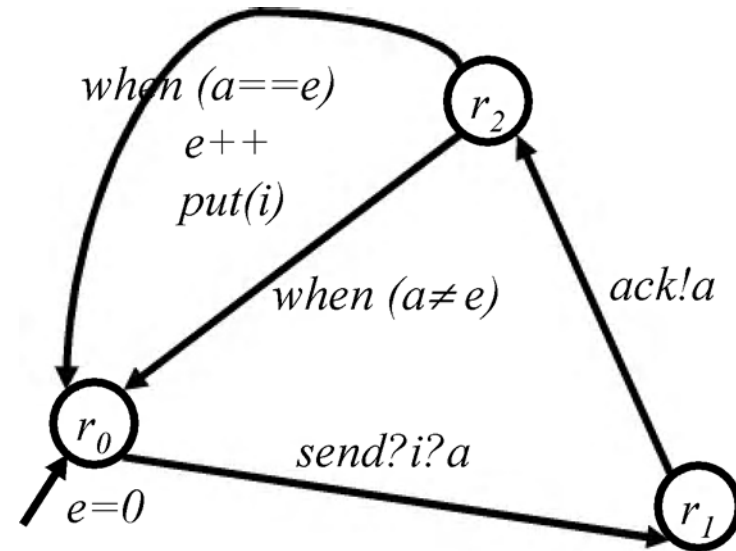
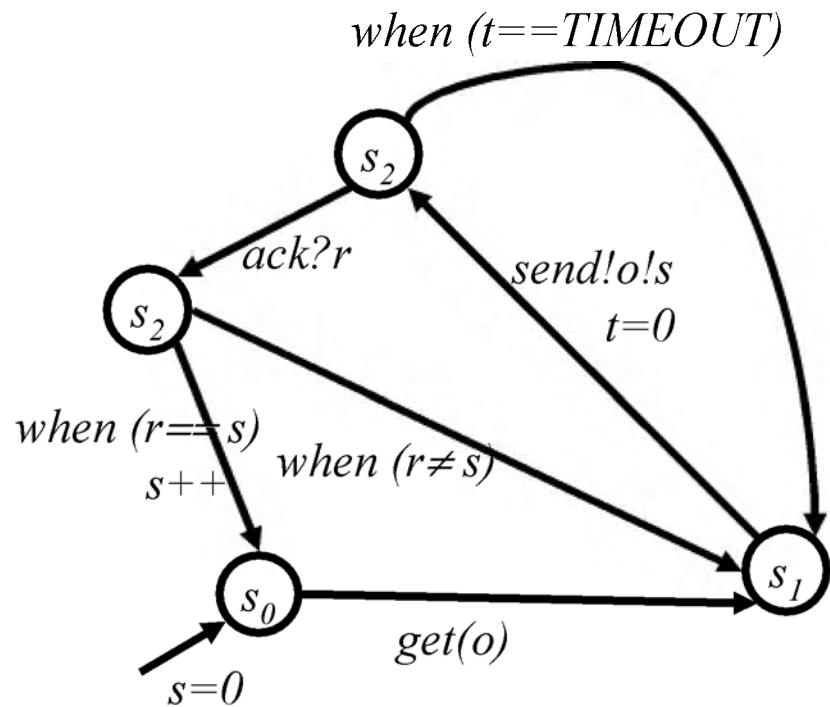
# Examples

abc...xyz



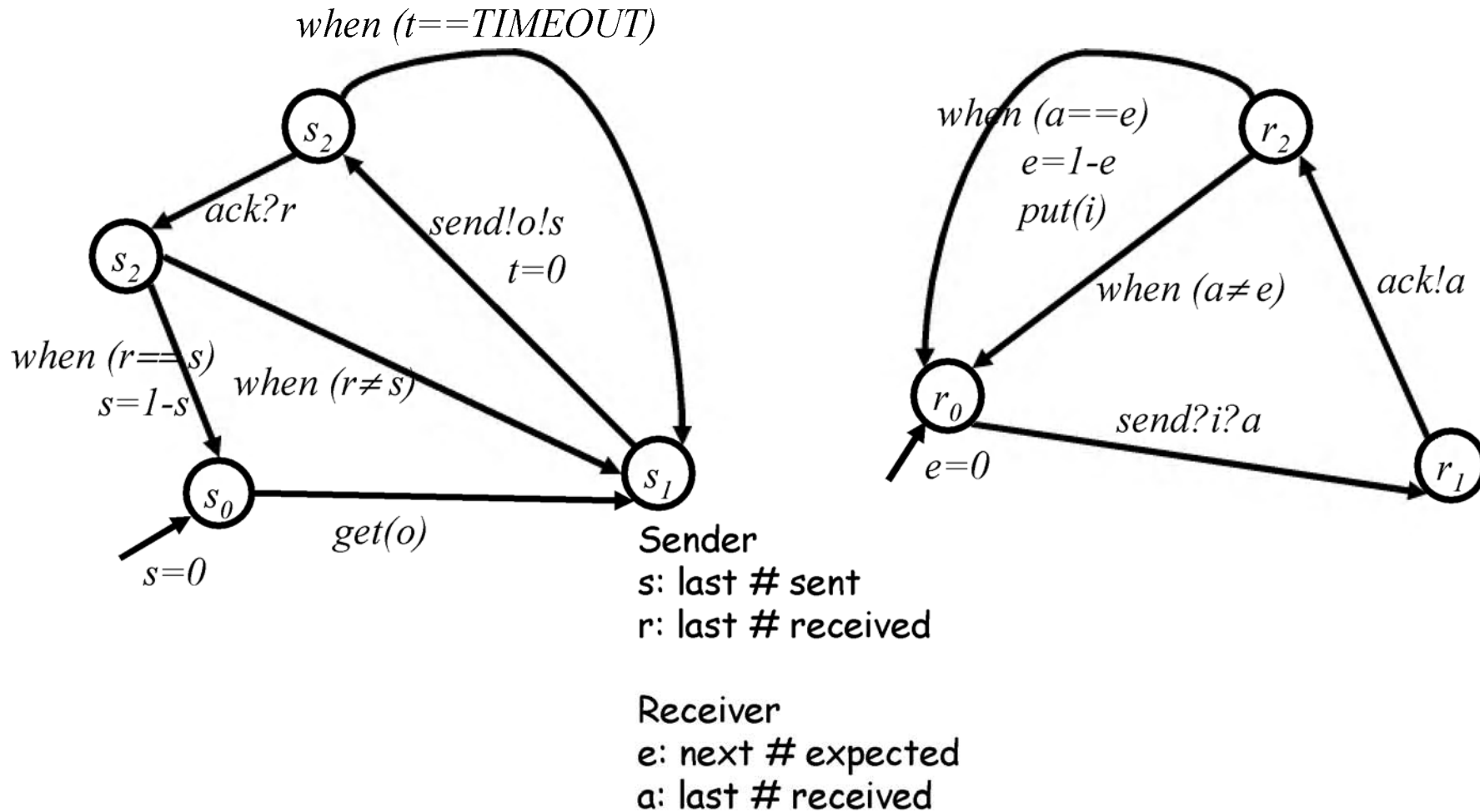


# Assessment:



- ❑ Believe it, or not. But this one works.
- ❑ Still it is a little suboptimal, because the sequence number grow, and thus eat up transmission capacity.

# 6th Revision: Just two sequence numbers

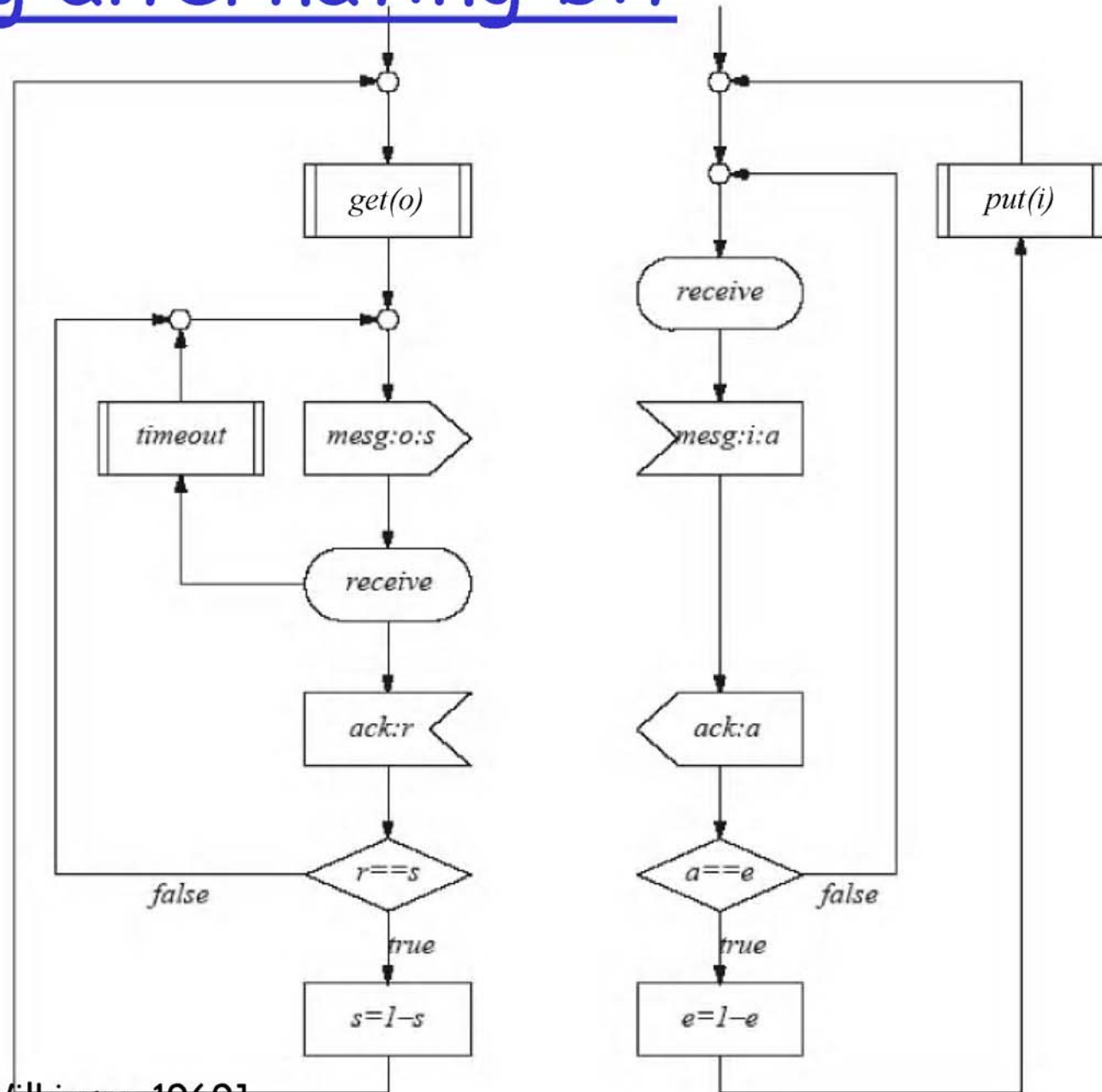


□ This one alternates a single bit, and still it works!



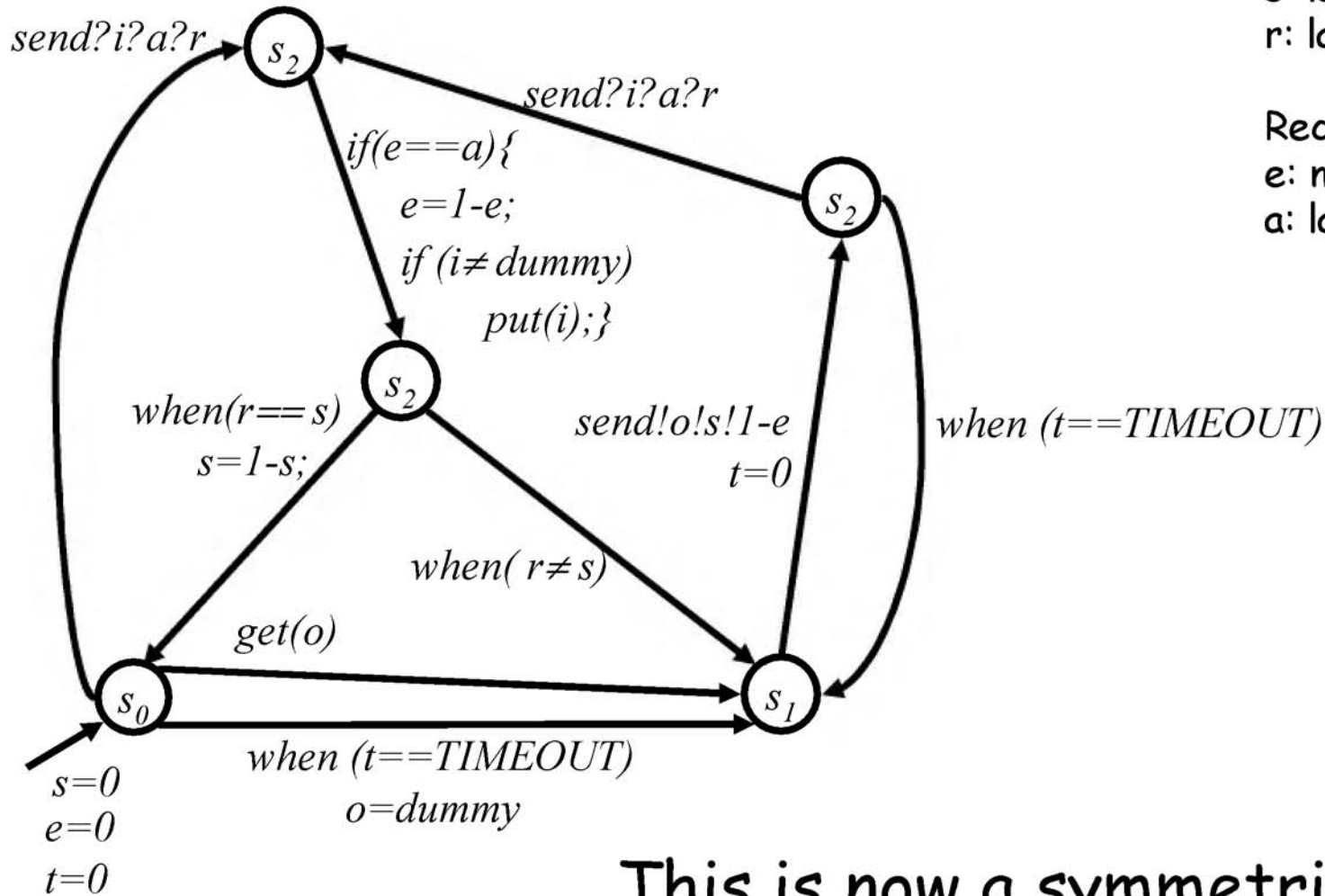
# The amazing alternating bit protocol

A bullet-proof protocol.



[ Bartlett, Scantlebury and Wilkinson 1969].

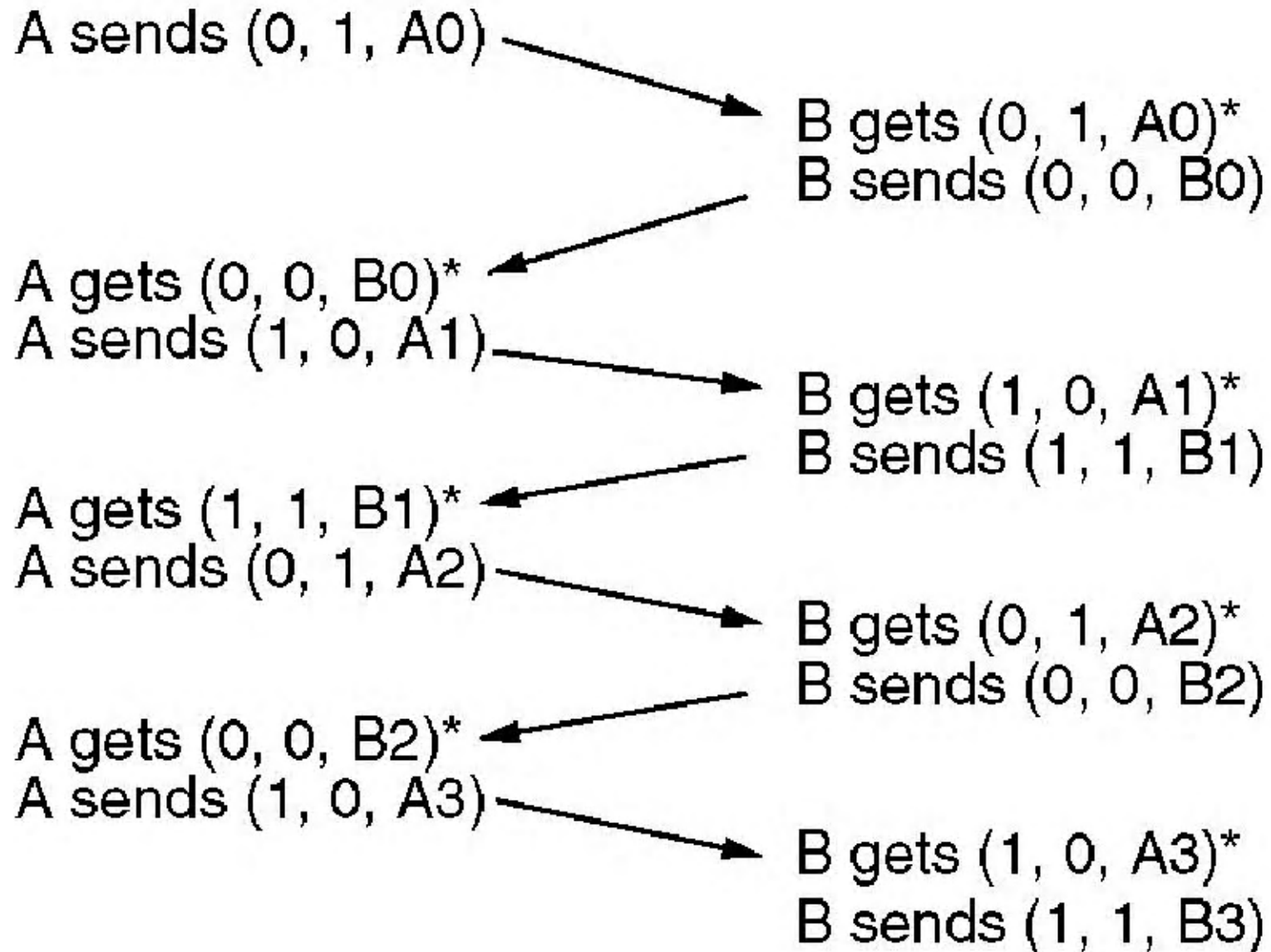
# 7th Revision: Alternating bit with full duplex and piggybacking

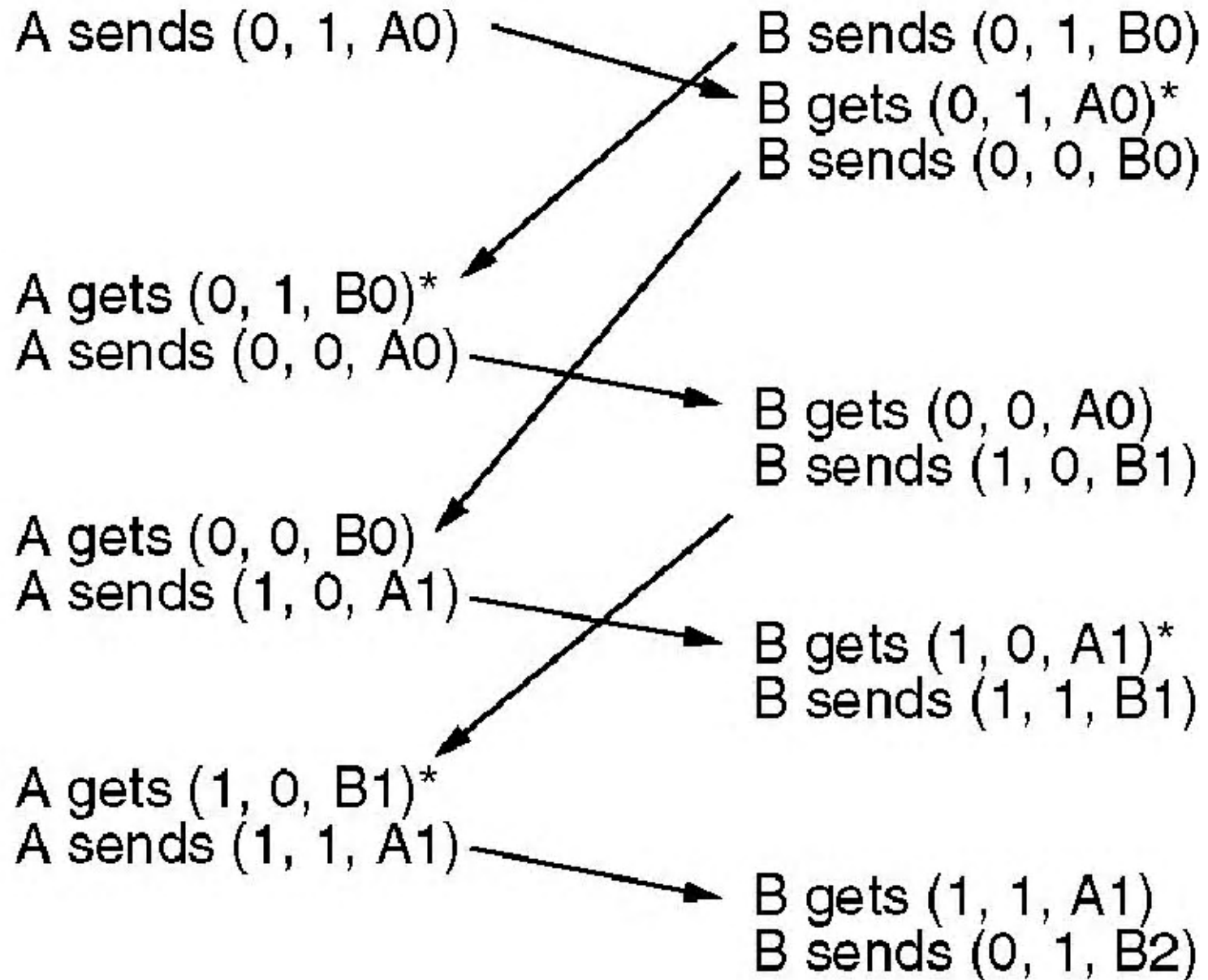


Sender part  
 s: last # sent  
 r: last # received

Receiver part  
 e: next # expected  
 a: last # received

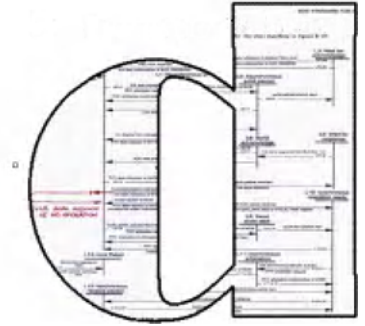
This is now a symmetric protocol.





# Assessment:

- You assess it.



# Networking

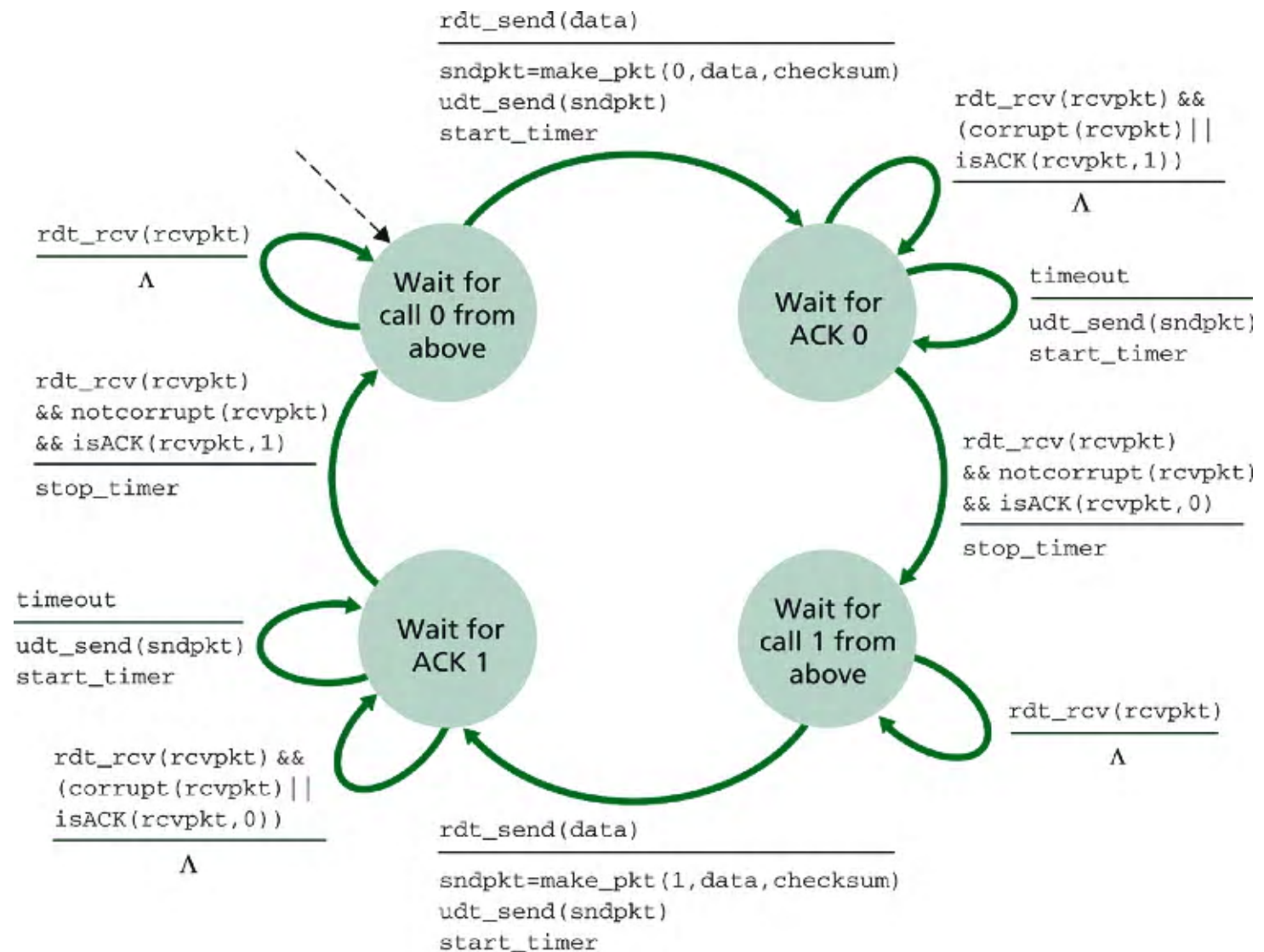
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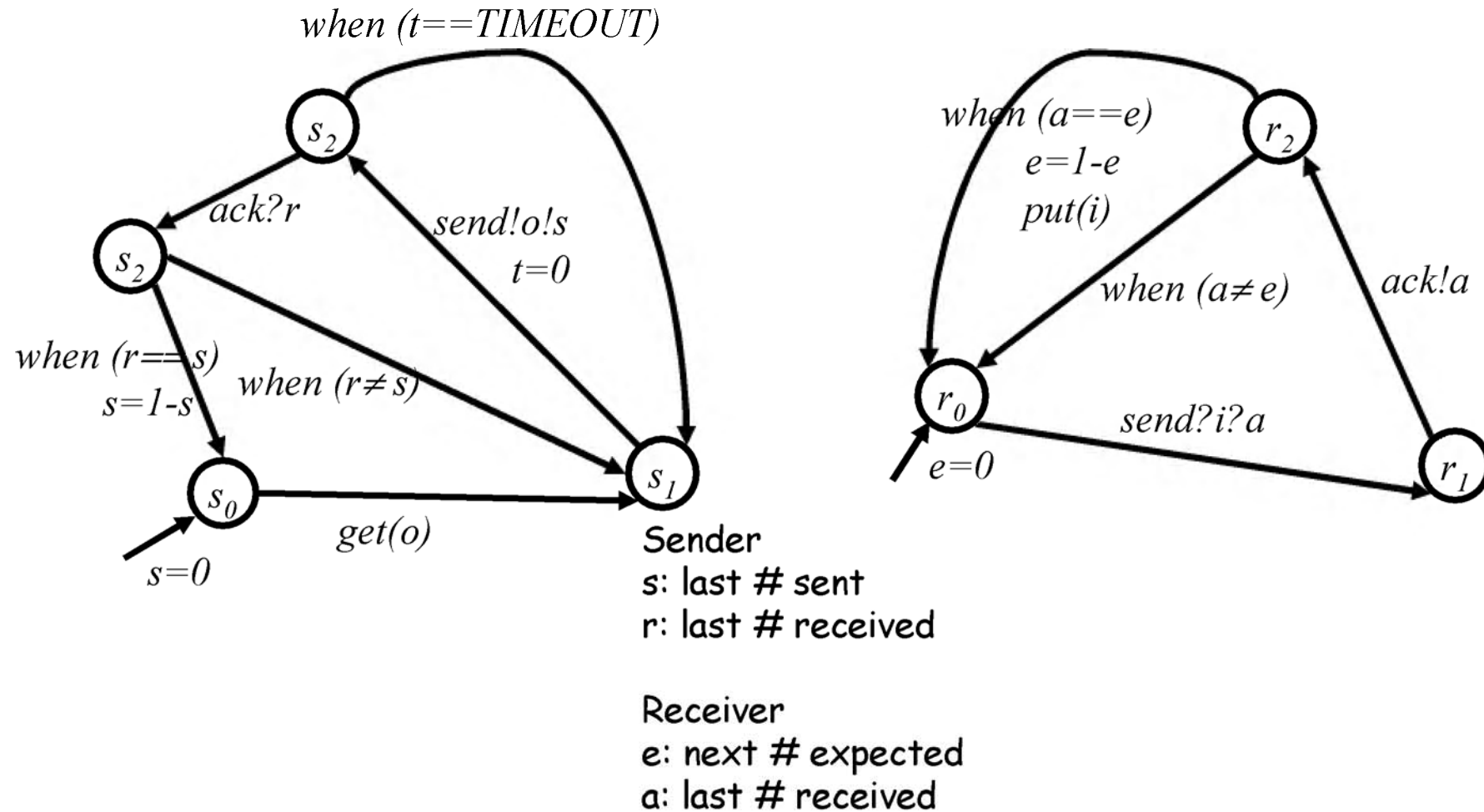
Summer 04

Lecture 5: Transport Layer

# rdt3.0 sender of [Kurose Ross]: The Alternating Bit protocol



# Recall the Alternating-Bit Protocol



□ This one alternates a single bit, and still it works!

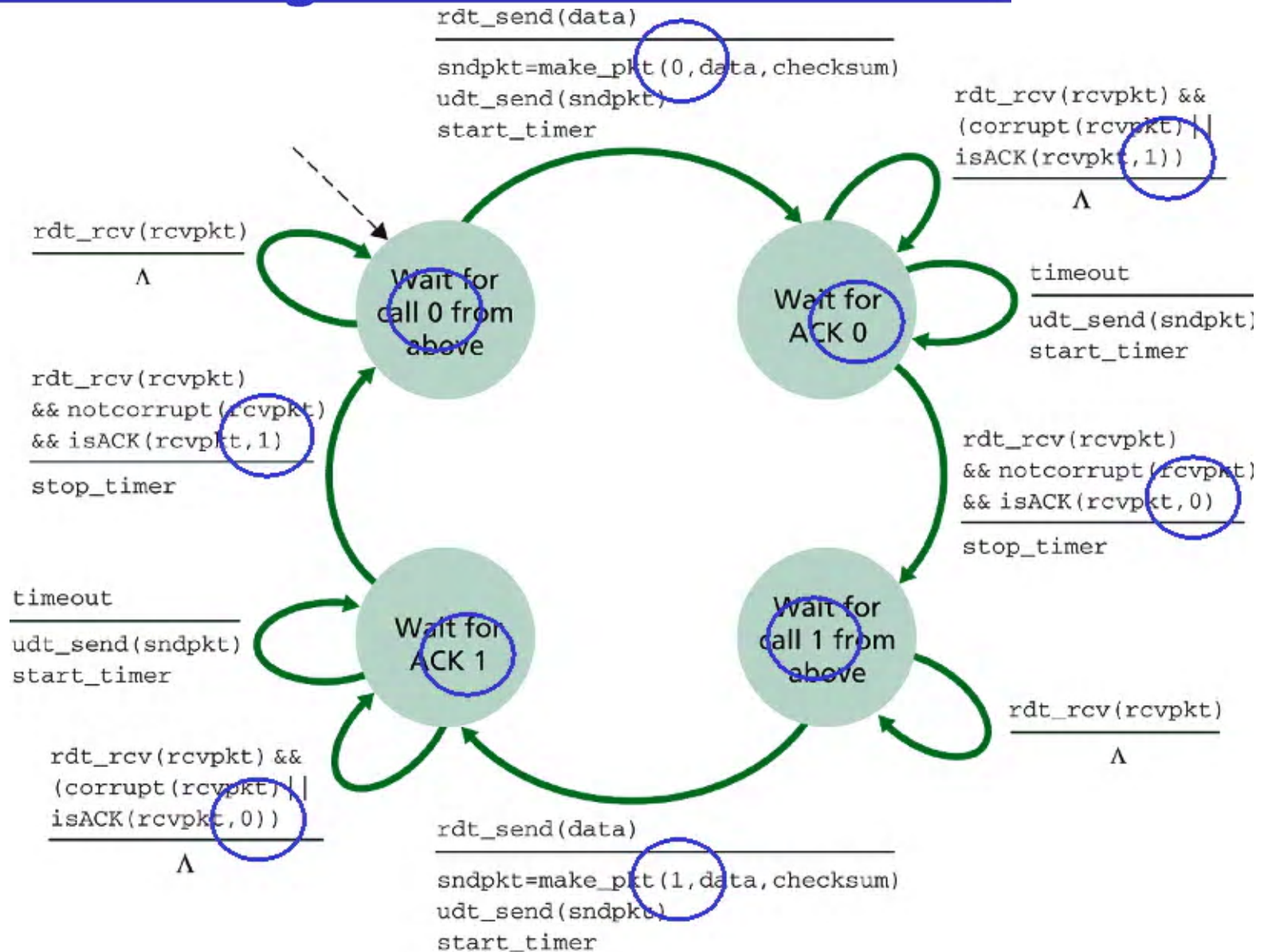




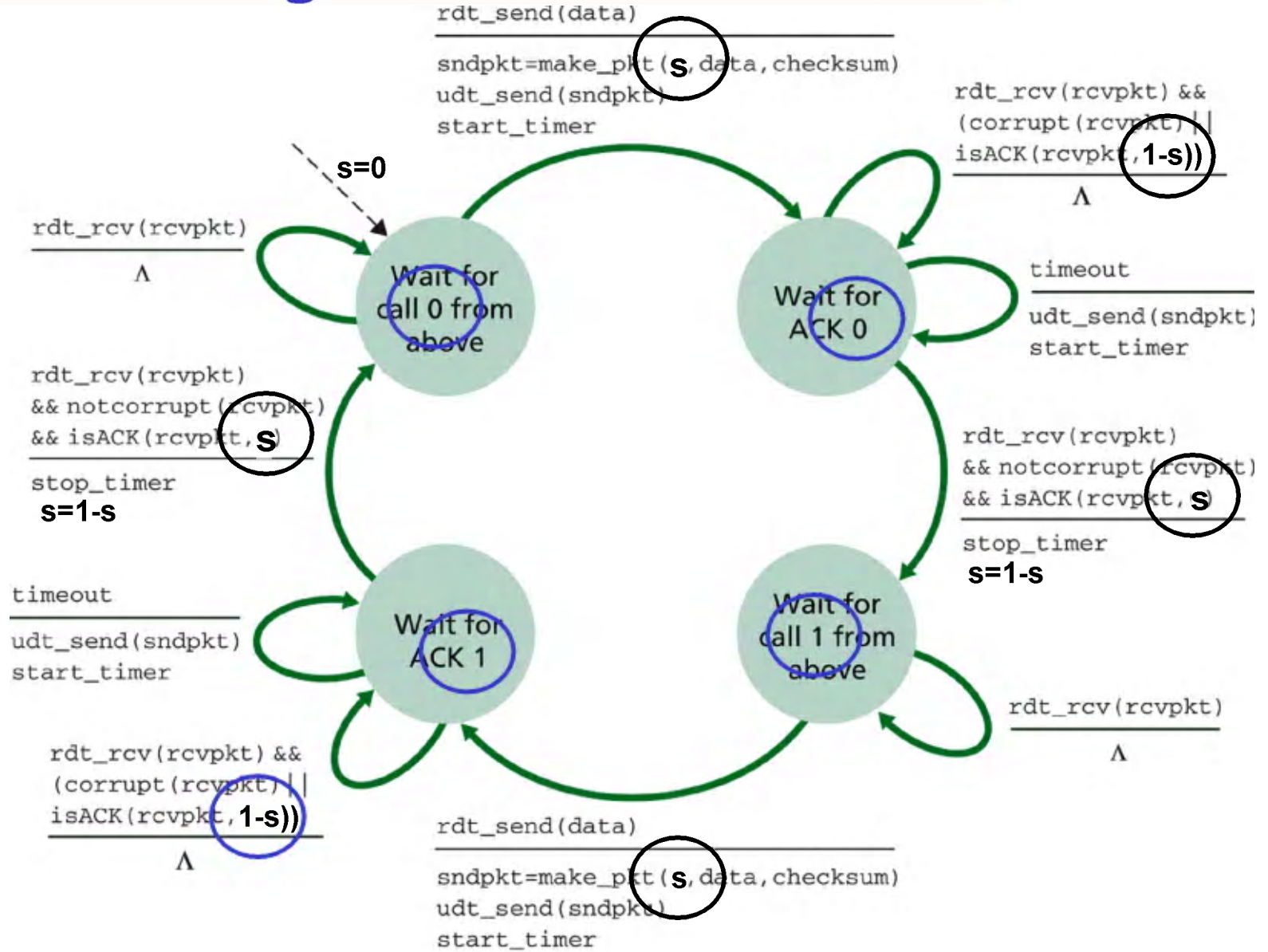
# A step-by-step transformation

- We'll go through a sequence of transformation steps for the two state-transition diagrams.
- 
- Each step will be presented informally.
- A formal treatment requires a **homomorphism** from one diagram to the other.
- **Homomorphism:**  
property-preserving mapping
- here properties are: traces (e.g. sequence diagrams) generated by either specification (in interaction with the receiver side)
- for any trace generated in one mode, there should be a homomorphic trace in the other model, and vice versa.

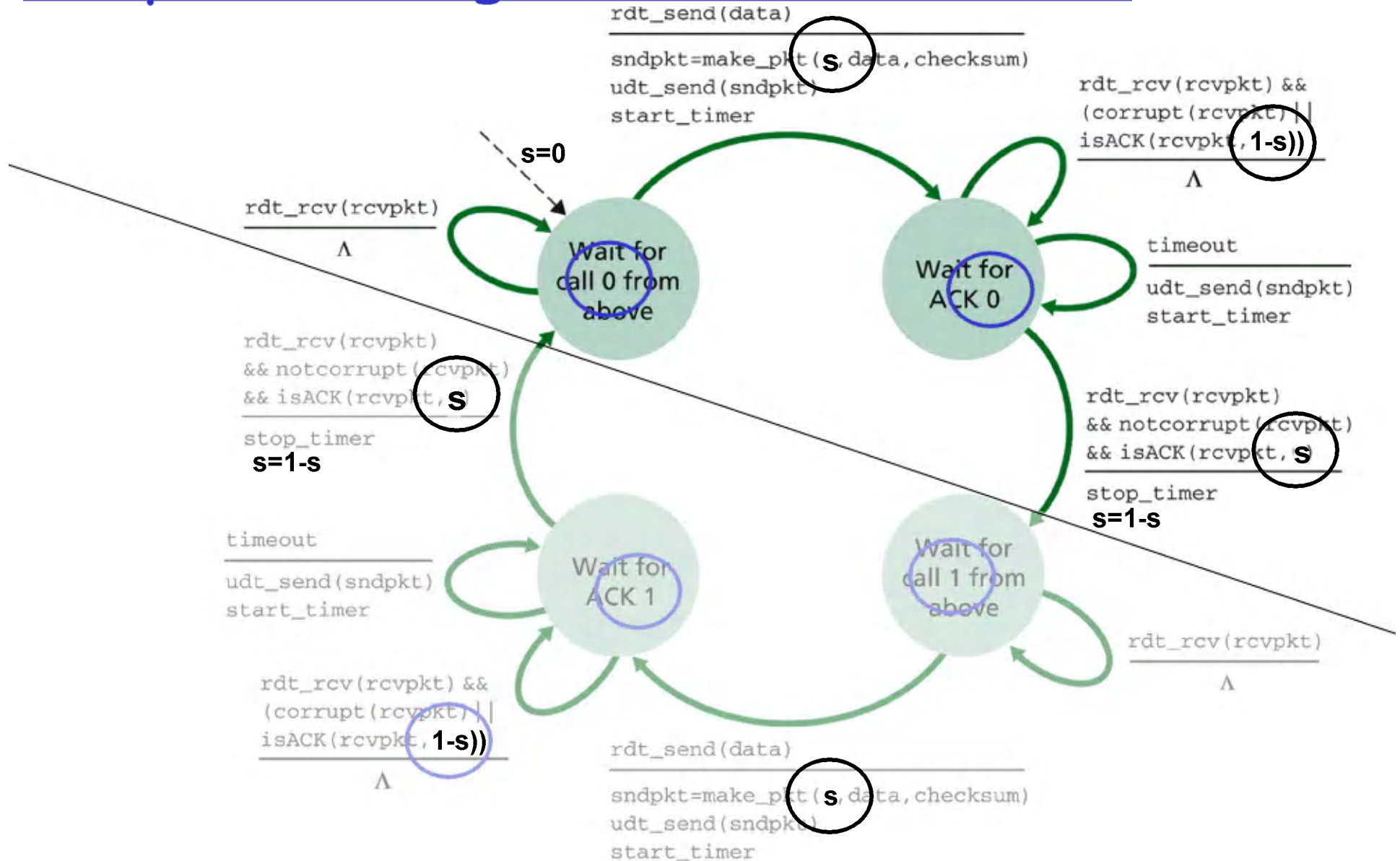
# Step I: Folding the alternation bit



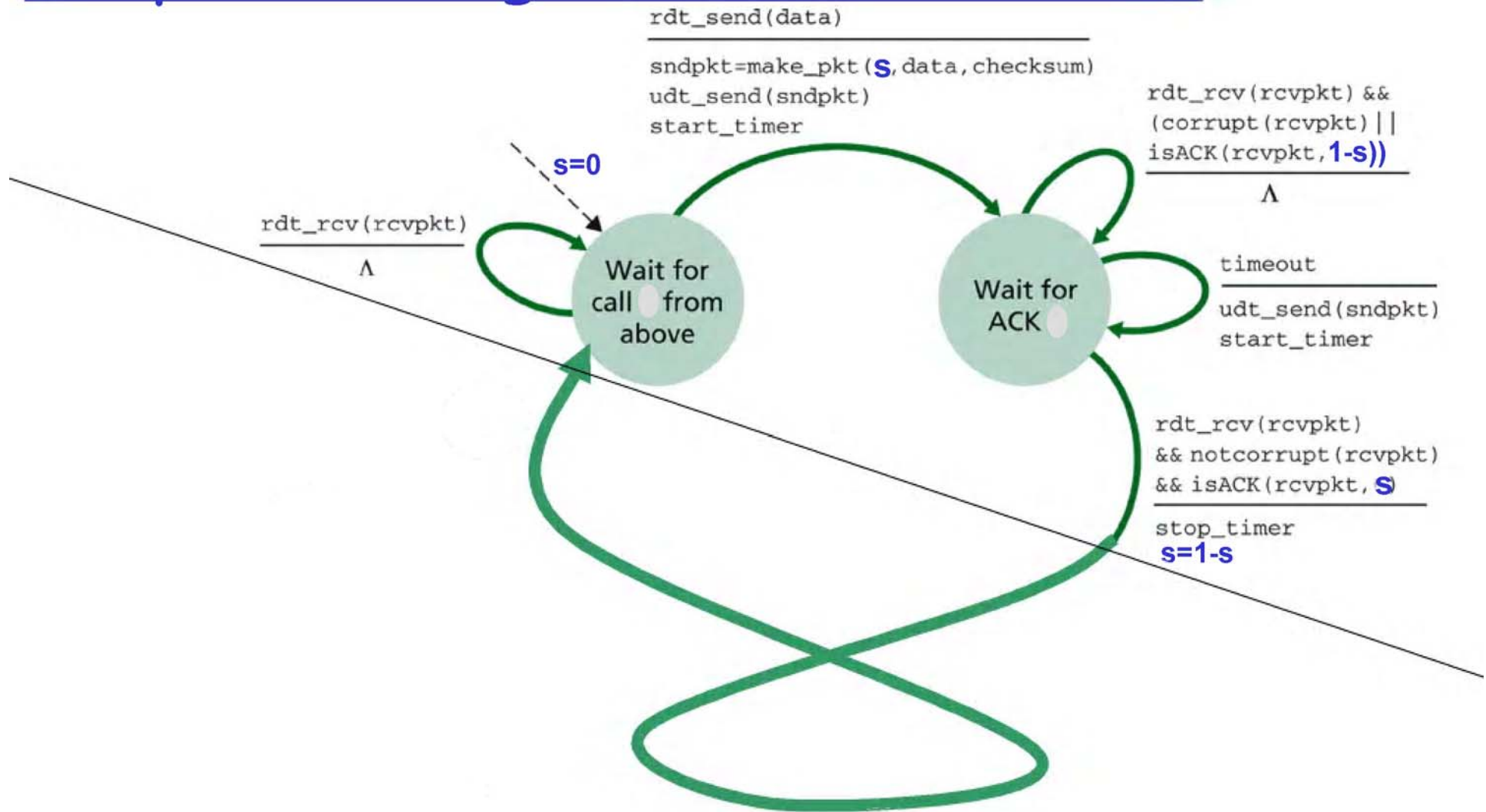
# Step I: Folding the alternation bit



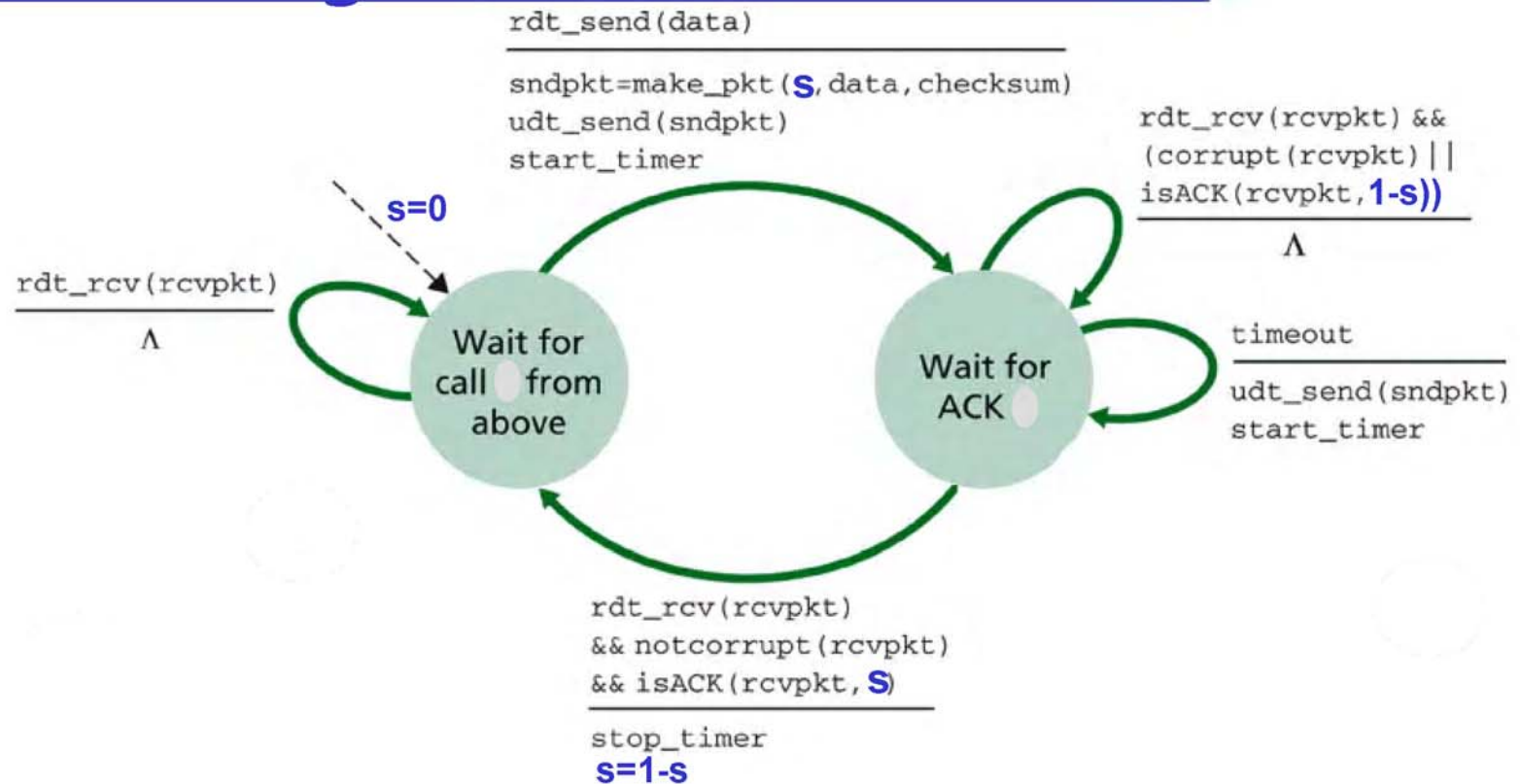
# Step I: Folding the alternation bit



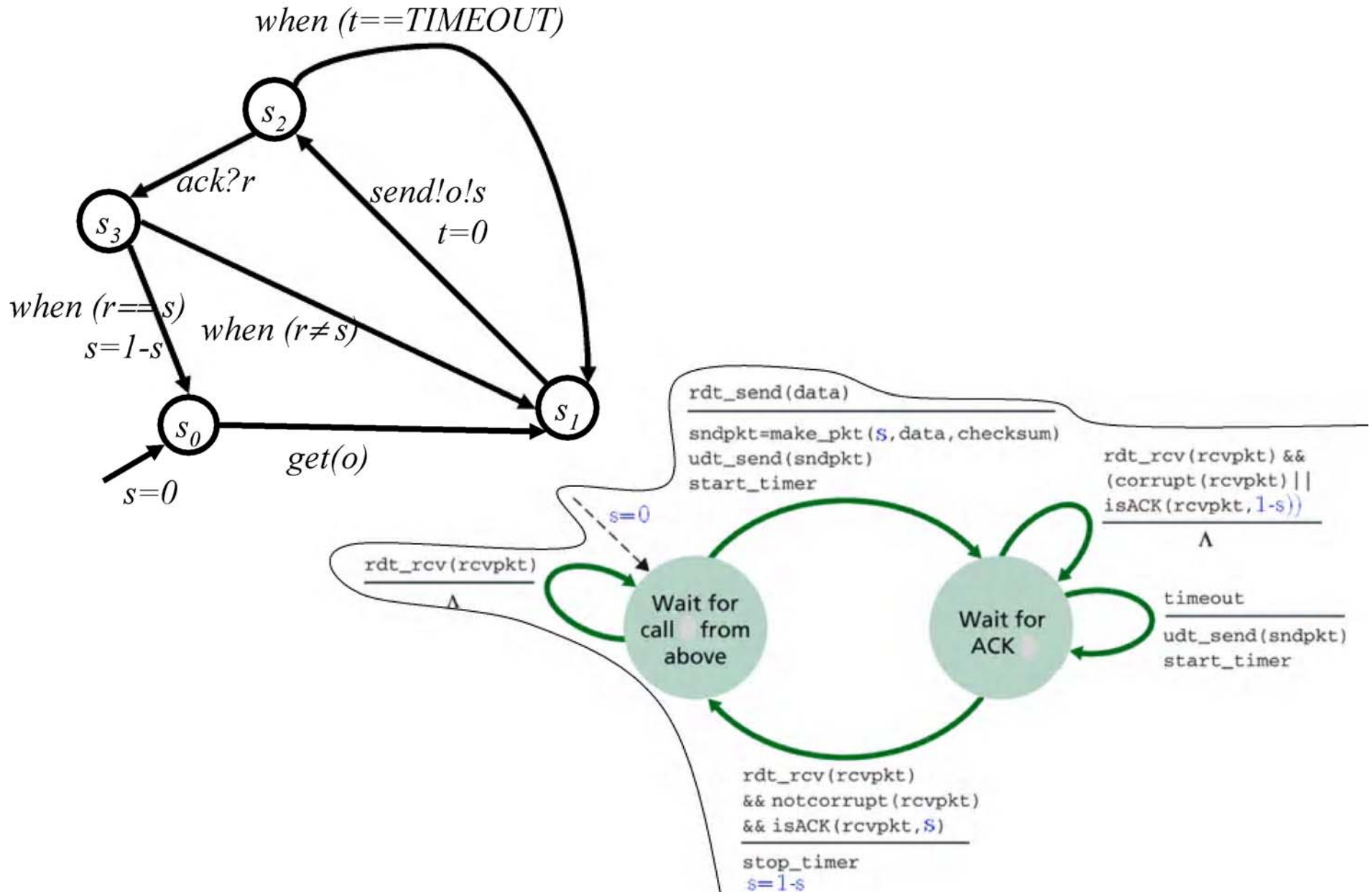
# Step I: Folding the alternation bit



# Step I: Folding the alternation bit

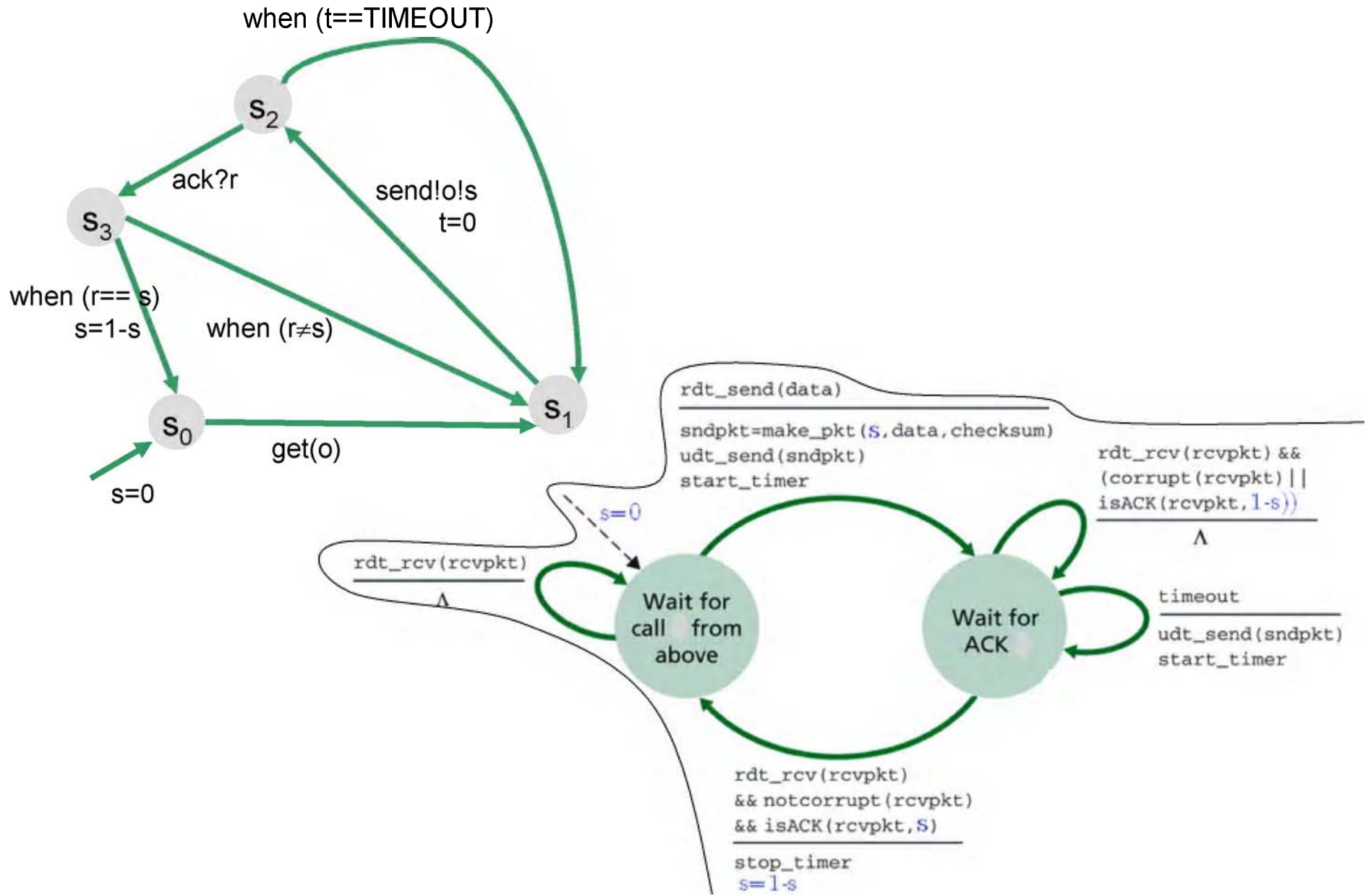


# Step I: Folding the alternation bit

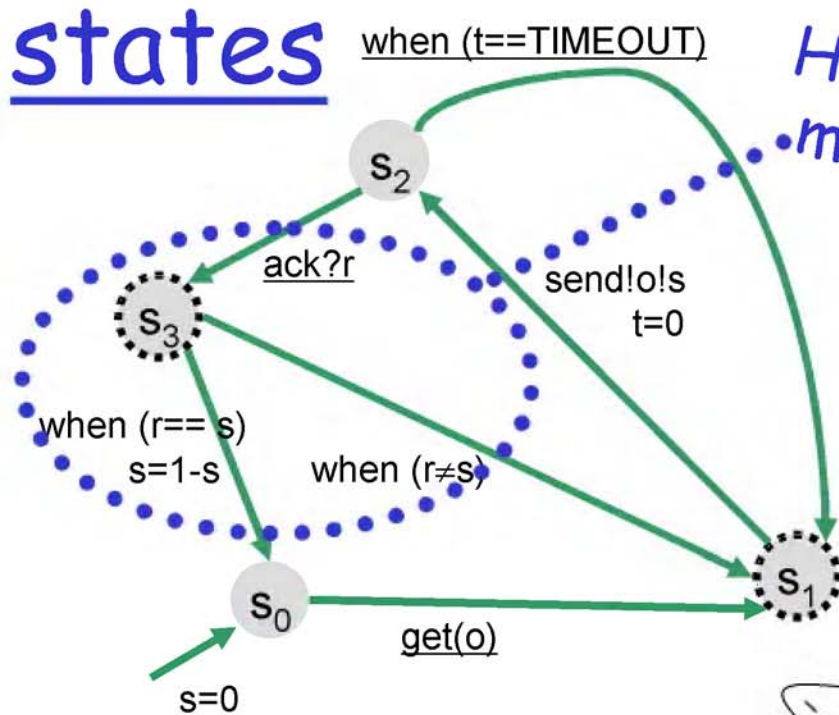




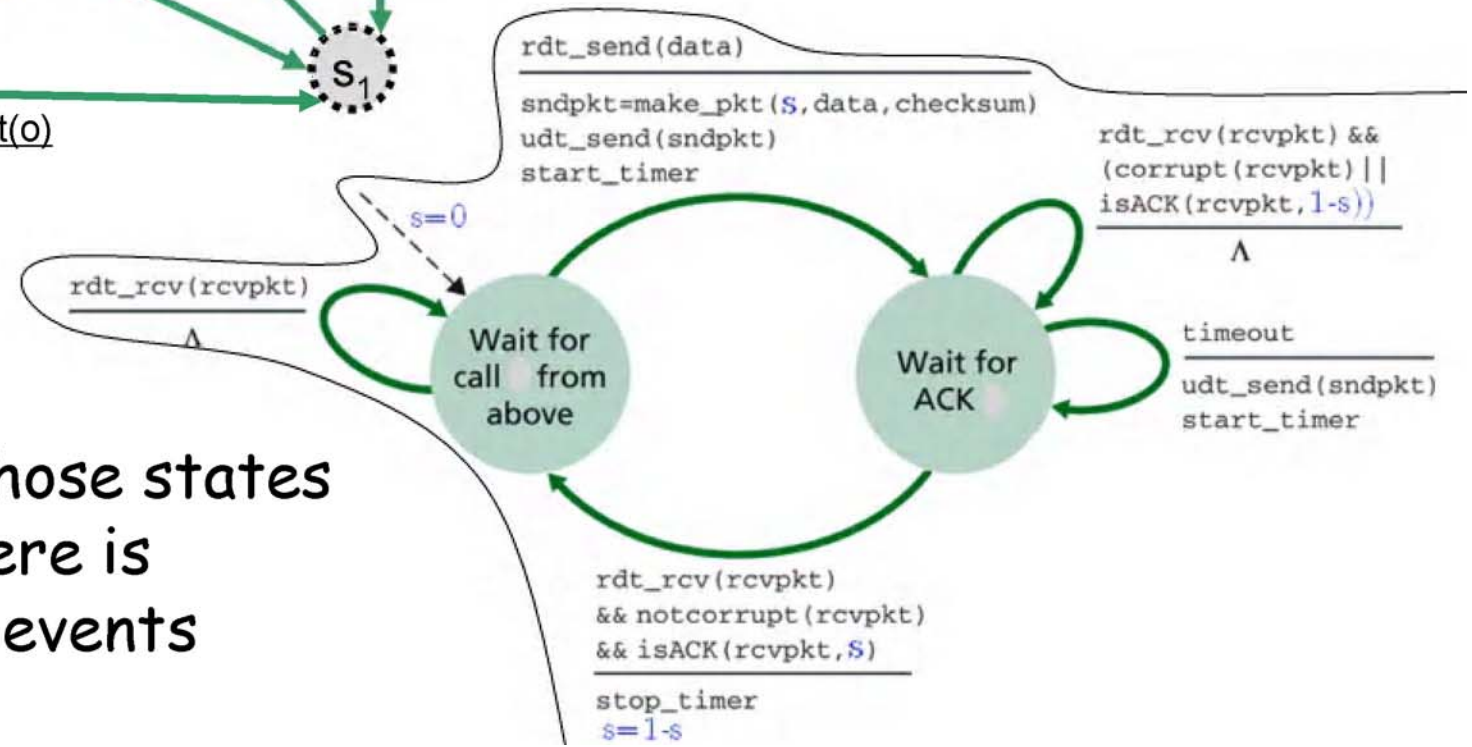
# Step II: Fontification & Colouring



# Step III: Getting rid of 'immaterial' states

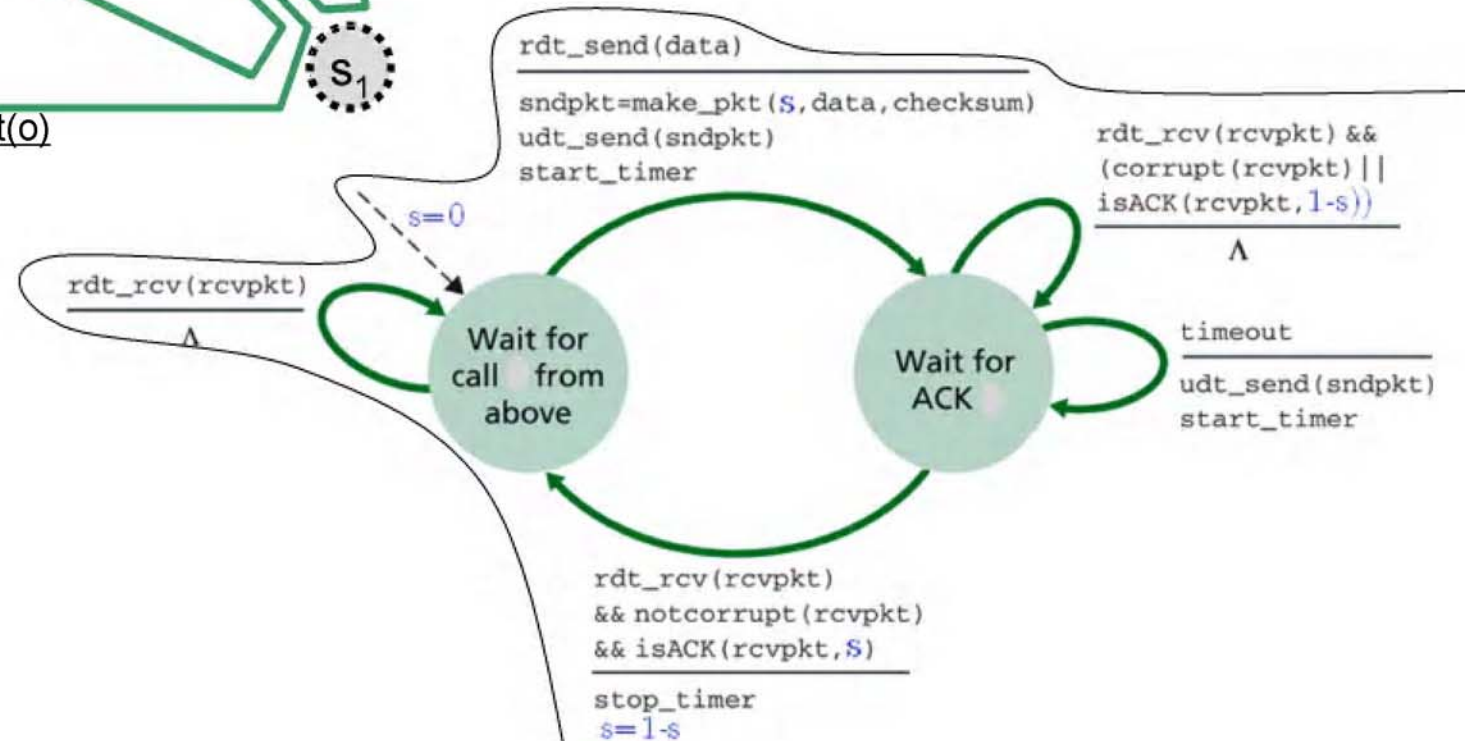
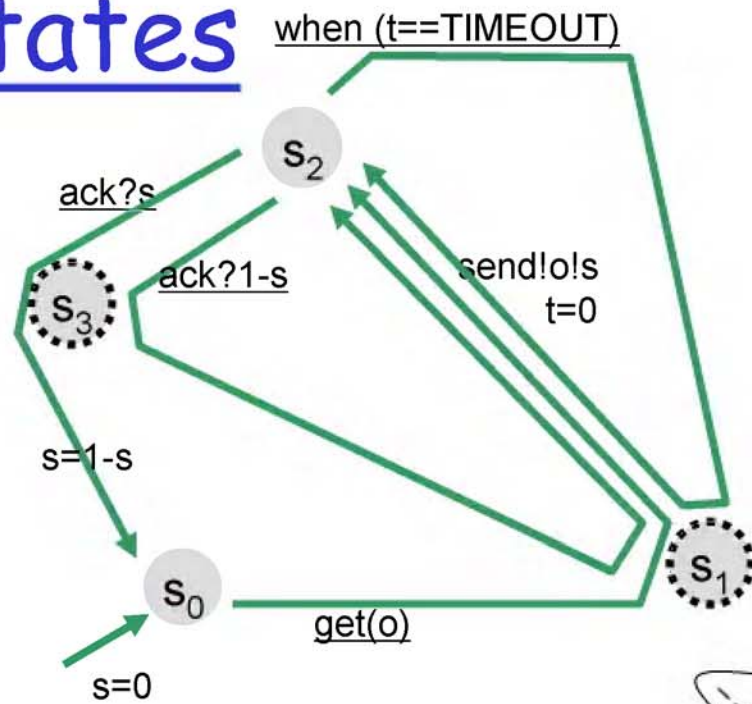


*Here there is a bit of a catch which may need some separate discussion*

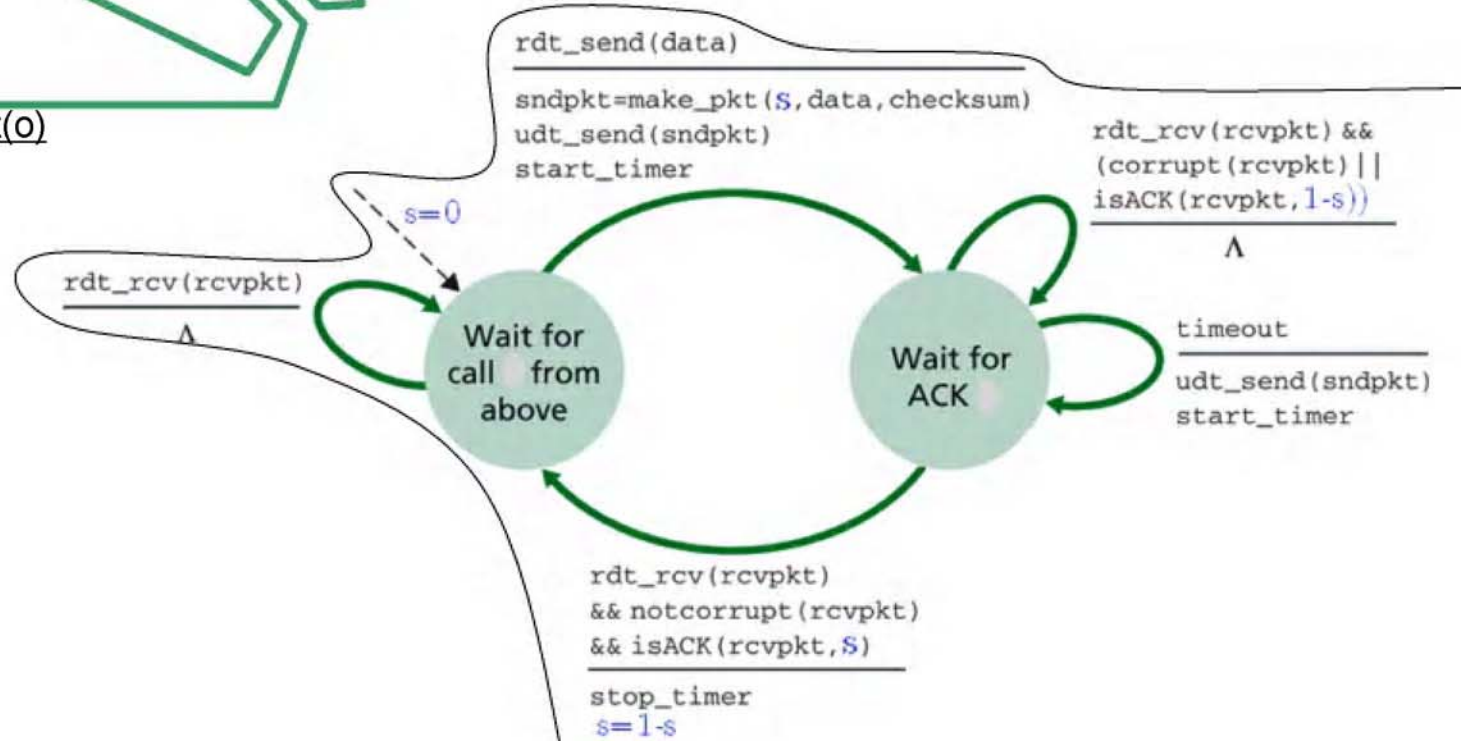
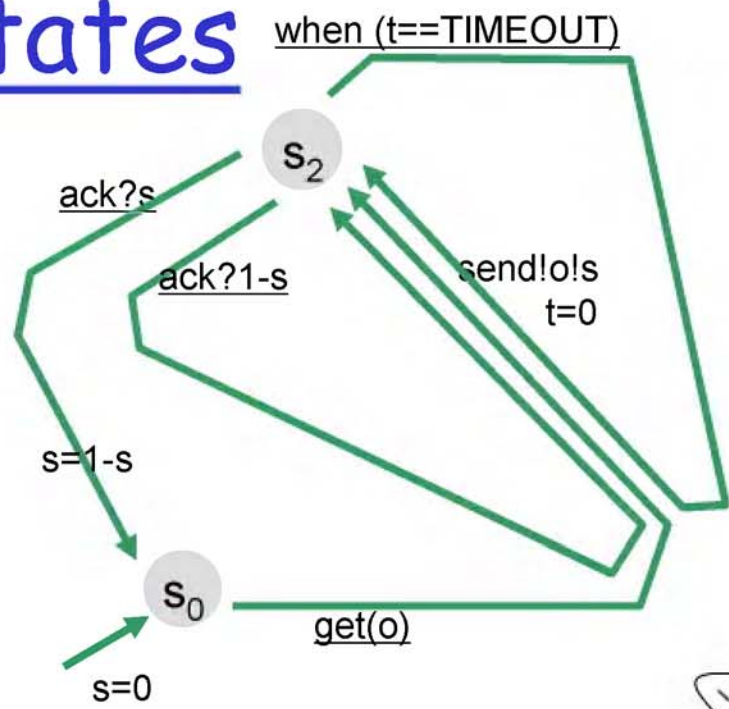


Keep only those states in which there is waiting for events

# Step III: Getting rid of 'immaterial' states



# Step III: Getting rid of 'immaterial' states



# A note on value passing and value testing

- The principal use of

$\langle \text{name} \rangle ? \langle v_1 \rangle ? \langle v_2 \rangle ? \dots ? \langle v_n \rangle$   
 ↘ variables!

is to receive data values via

$\langle \text{name} \rangle ! \langle d_1 \rangle ! \langle d_2 \rangle ! \dots ? \langle d_n \rangle$   
 ↘ values!

- You may also write this as

$\langle \text{name} \rangle ? (\langle v_1 \rangle, \langle v_2 \rangle, \dots, \langle v_n \rangle)$

and

$\langle \text{name} \rangle ! (\langle d_1 \rangle, \langle d_2 \rangle, \dots, \langle d_n \rangle)$

- However you write it, after a successful reception, the variables  $v_1, \dots, v_n$  hold the values  $d_1, \dots, d_n$

This is called **value passing**.

- One may also mix variables and constants, as in

$\langle \text{name} \rangle ? \langle v_1 \rangle ? \langle d \rangle ? \langle v_2 \rangle ? \dots ? \langle v_n \rangle$

- In this case communication is only successful if the very same 'd' is offered by the sender, as in

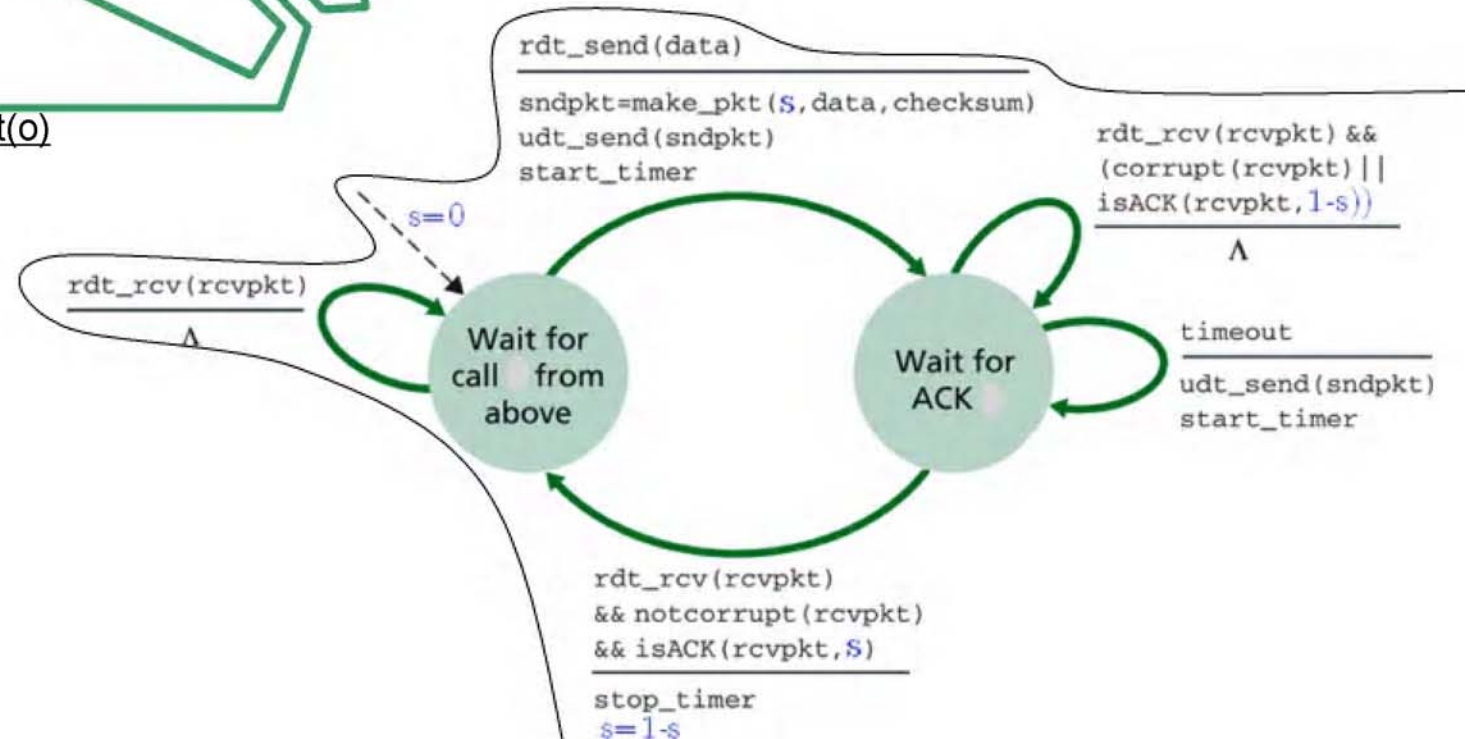
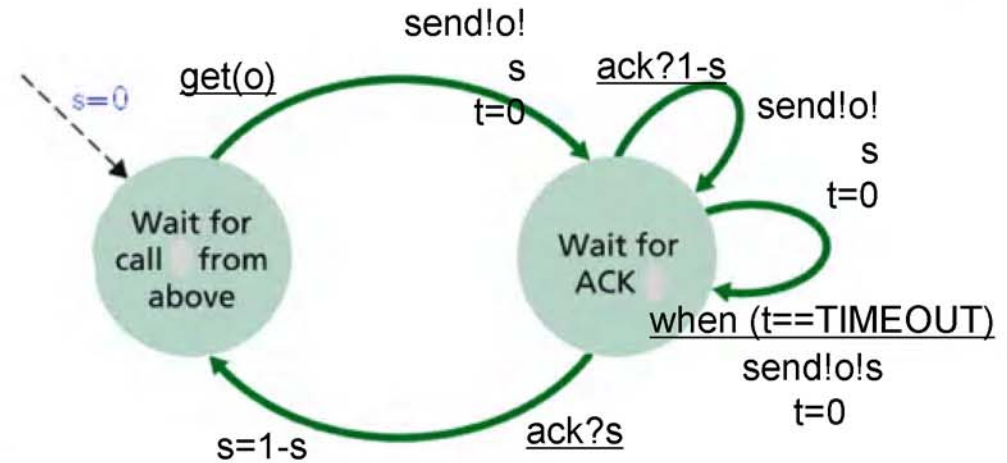
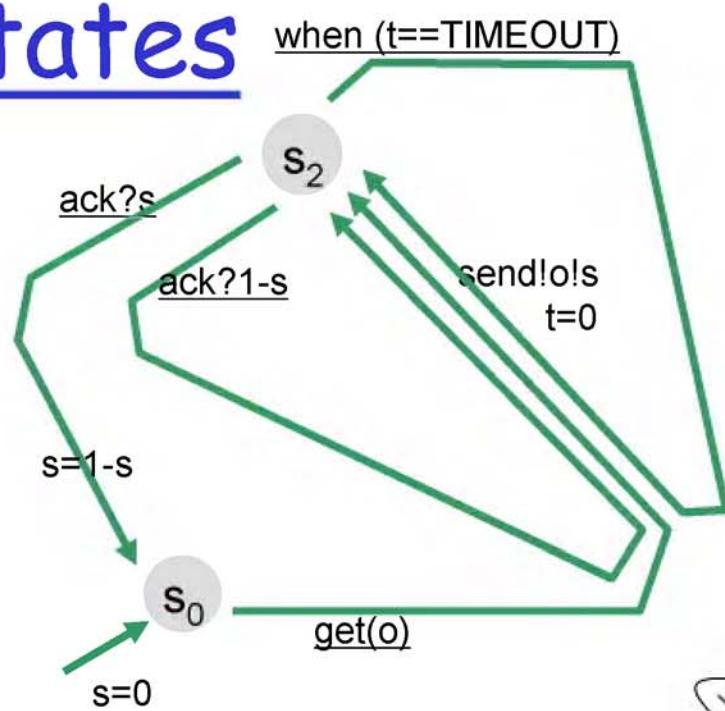
$\langle \text{name} \rangle ! \langle d_1 \rangle ! \langle d \rangle ! \langle d_2 \rangle ! \dots ! \langle d_n \rangle$

- If the offered and the expected 'd's are different, communication is impossible, and no state transition will be taken.

This is called **value testing**.

More on this e.g. in [Holzmann 91/03]

# Step IV: Relabelling and rearranging states



- s<sub>0</sub> ! Wait for call from above
- s<sub>2</sub> ! Wait for ACK

# Step V: Relabelling transitions

get(o) !     rdt\_send(data)

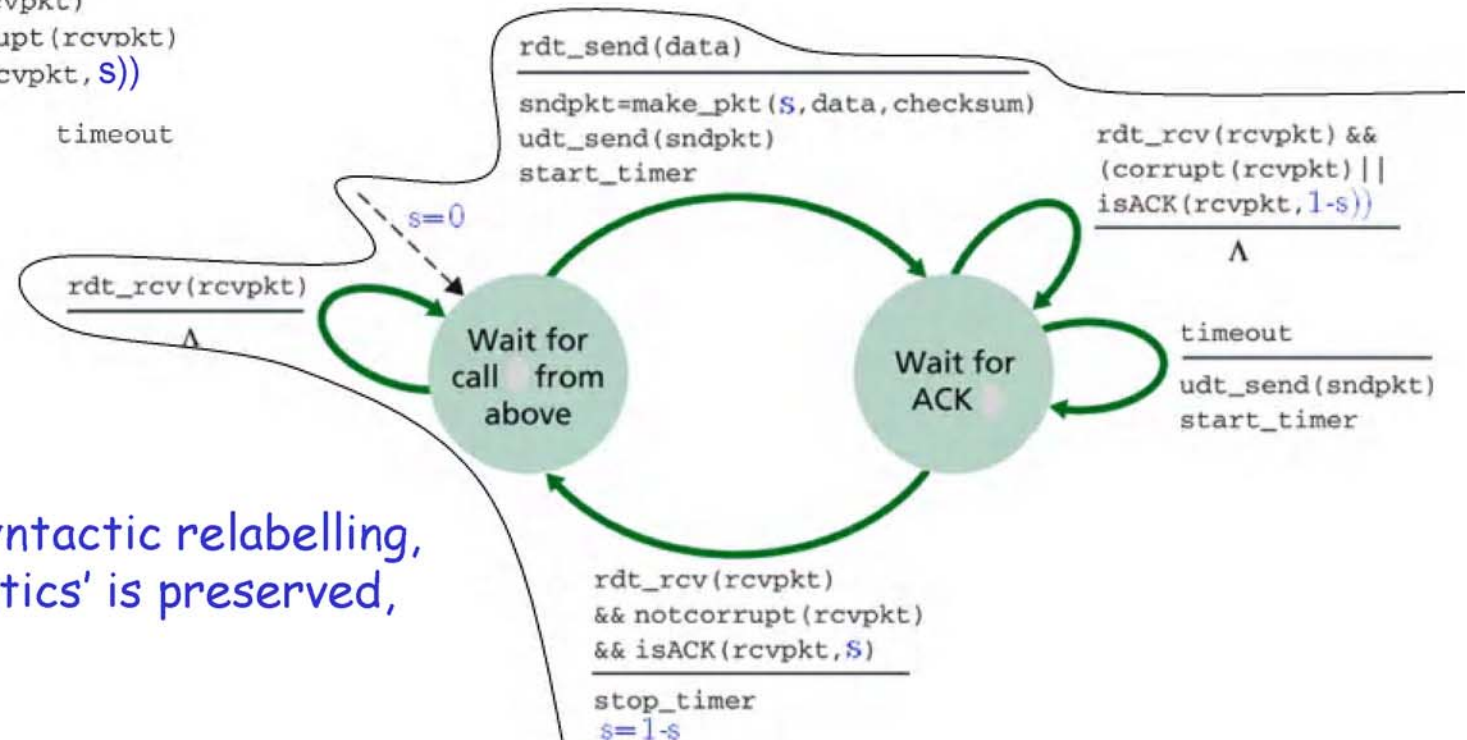
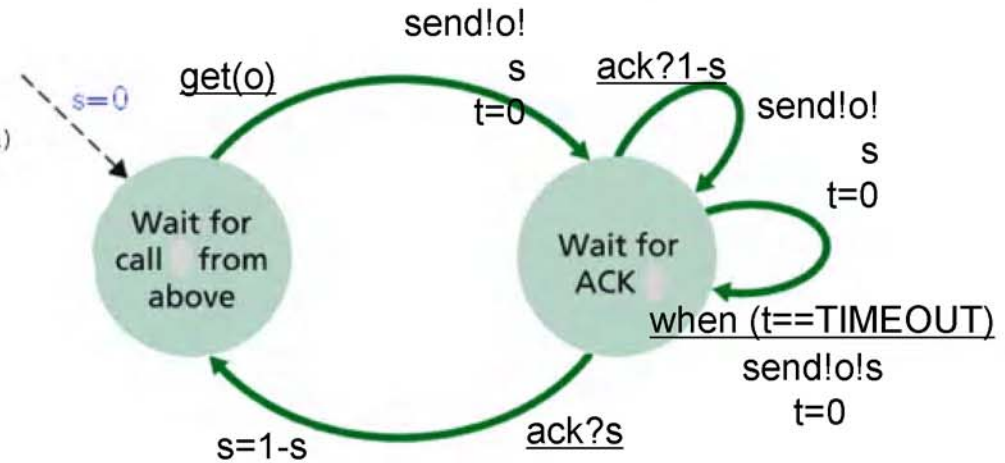
send ! o ! s !     sndpkt=make\_pkt (S, data, checksum)  
                          udt\_send(sndpkt)

t = 0 !     start\_timer

ack ? 1-s !     rdt\_rcv(rcvpkt) &&  
                          (corrupt(rcvpkt) ||  
                          isACK(rcvpkt, 1-s))

ack ? s !     rdt\_rcv(rcvpkt)  
                  && notcorrupt(rcvpkt)  
                  && isACK(rcvpkt, S))

when (t==TIMEOUT) !     timeout



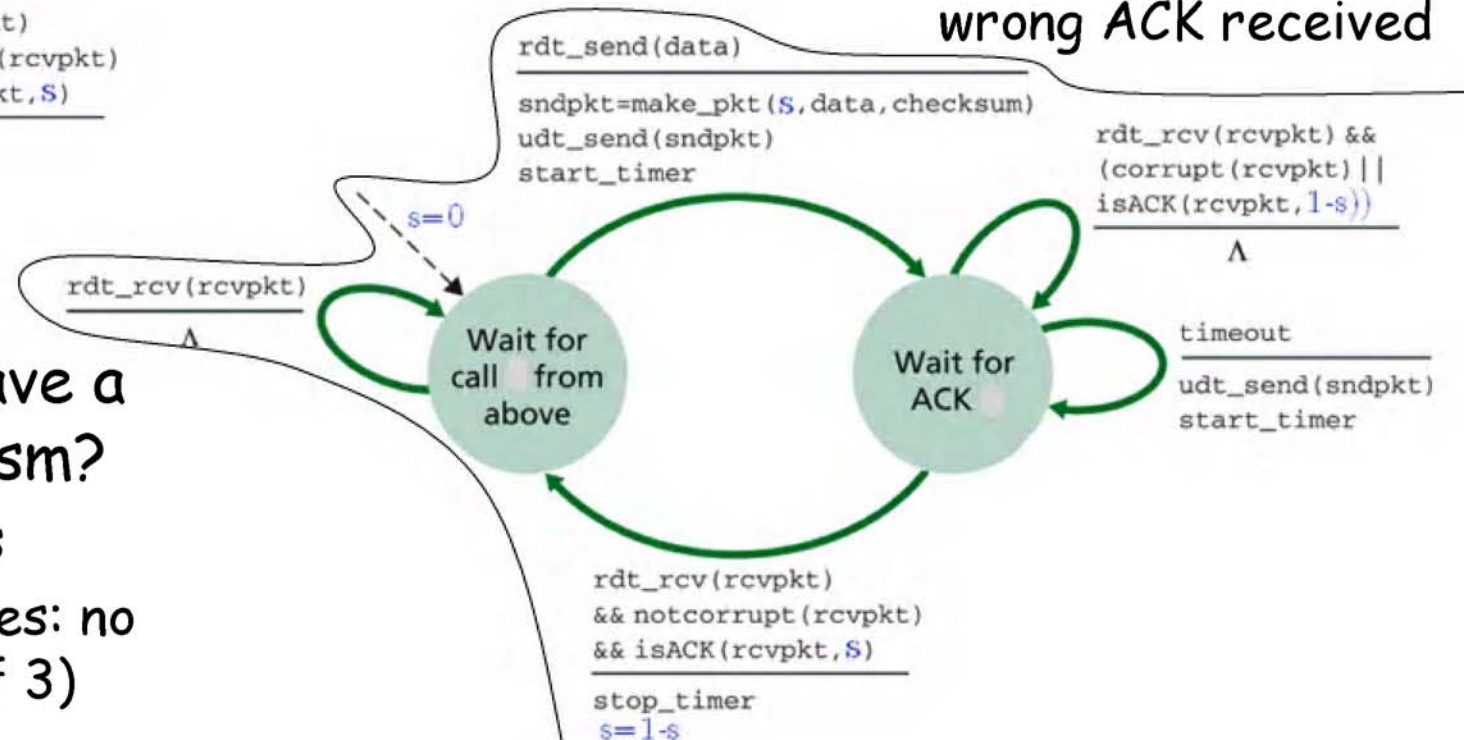
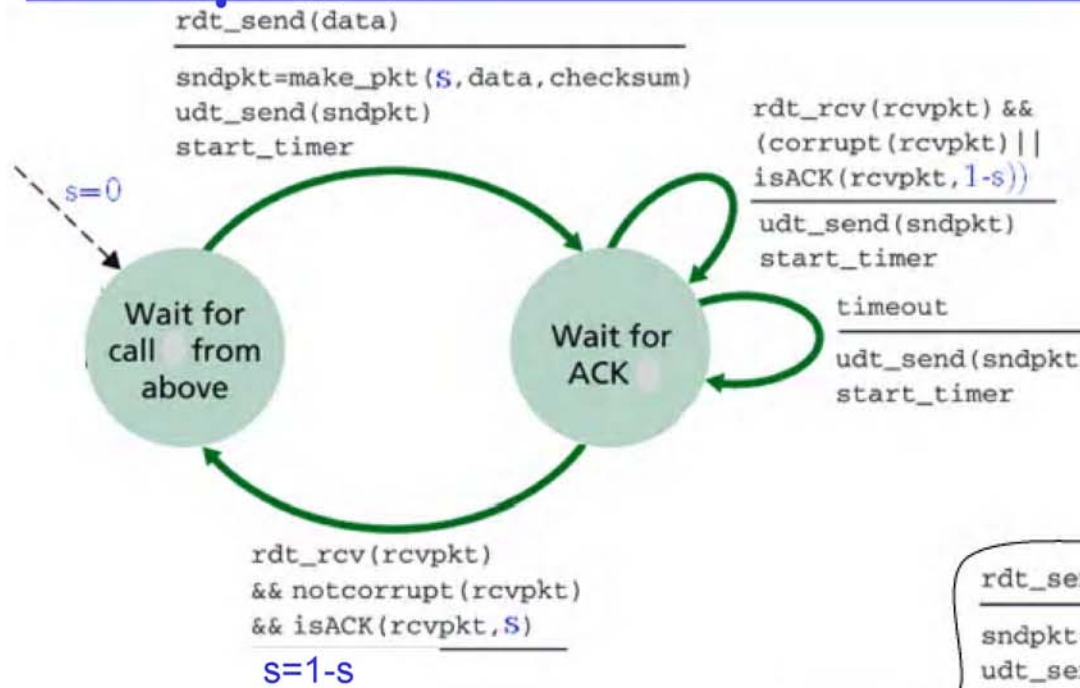
Note:  
this is more than syntactic relabelling,  
the 'intuitive semantics' is preserved,  
for instance:

o !     data

# Step VI: Check result

Find three differences?

1. no account for unexpected pkts when nothing to send
2. no timer stopping
3. no wait for timeout if wrong ACK received



- So, do we have a homomorphism?
  - Traces: yes
  - Timed traces: no (because of 3)



# rdt3.0 sender of [Kurose Ross]: The A-B protocol

